

Non-Gaussianity in data- and parameter space

Elena Sellentin

Institut für Theoretische Physik
Universität Heidelberg

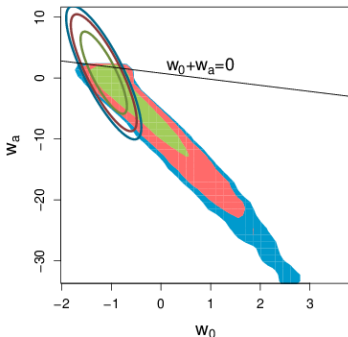
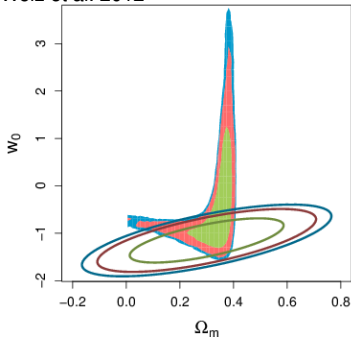
Gravity on the Largest Scales

Code public on github:
<http://Lnasellentin.github.io/DALI/>

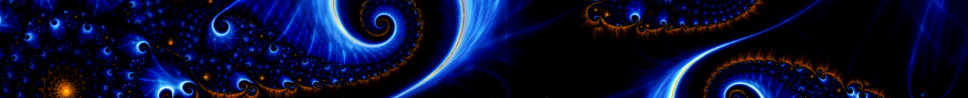
1000 SN 1a, vary Ω_m, w_0, w_a :

$$F_{\alpha\beta} = \mu_{,\alpha} C^{-1} \mu_{\beta}$$

Wolz et al. 2012



Often, higher order derivatives will exist and encode the non-Gaussianity of the likelihood.



Approximate a Likelihood

$$L = \exp(-\mathcal{L})$$

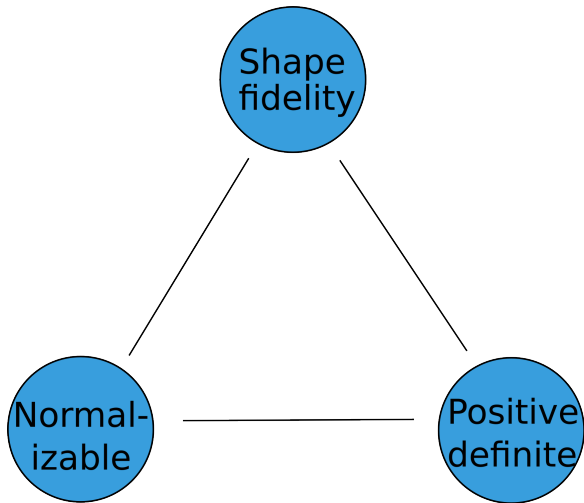
where

$$\mathcal{L} = \frac{1}{2} \text{Tr} \left[\ln(\mathbf{C}) + (\mathbf{d} - \boldsymbol{\mu}) \mathbf{C}^{-1} (\mathbf{d} - \boldsymbol{\mu}) \right]$$

It's not just a usual Taylor approximation!

It's a Taylor approximation under the additional constraints of **normalizability** and **positive-definiteness**.

Approximating a likelihood



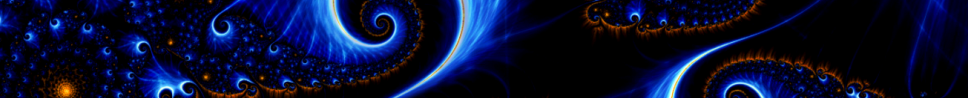
Derivative expansion: DALI

Expand the *mean* or the *covariance matrix*:

$$\boldsymbol{\mu}(\mathbf{p}) = \hat{\boldsymbol{\mu}} + \boldsymbol{\mu}_{,\alpha} \Delta p_{\alpha} + \frac{1}{2} \boldsymbol{\mu}_{,\alpha\beta} \Delta p_{\alpha} \Delta p_{\beta} + \frac{1}{3!} \boldsymbol{\mu}_{,\alpha\beta\delta} \Delta p_{\alpha} \Delta p_{\beta} \Delta p_{\delta} \dots$$

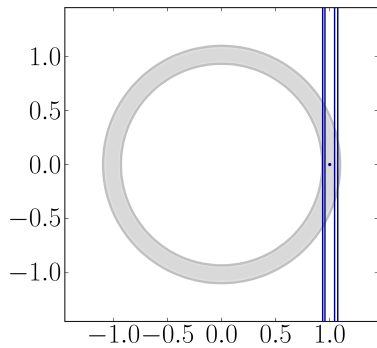
$$\mathbf{C}(\mathbf{p}) = \hat{\mathbf{C}} + \mathbf{C}_{,\alpha} \Delta p_{\alpha} + \frac{1}{2} \mathbf{C}_{,\alpha\beta} \Delta p_{\alpha} \Delta p_{\beta} + \frac{1}{3!} \mathbf{C}_{,\alpha\beta\gamma} \Delta p_{\alpha} \Delta p_{\beta} \Delta p_{\gamma} \dots$$

$$P \approx N \exp \left[-\frac{1}{2} (\mathbf{d} - \hat{\boldsymbol{\mu}} - \boldsymbol{\mu}_{,\alpha} \Delta p_{\alpha} - \frac{1}{2} \boldsymbol{\mu}_{,\alpha\beta} \Delta p_{\alpha} \Delta p_{\beta} - \dots) \mathbf{C}^{-1} (\mathbf{d} - \hat{\boldsymbol{\mu}} - \boldsymbol{\mu}_{,\alpha} \Delta p_{\alpha} - \frac{1}{2} \boldsymbol{\mu}_{,\alpha\beta} \Delta p_{\alpha} \Delta p_{\beta} - \dots) \right]$$



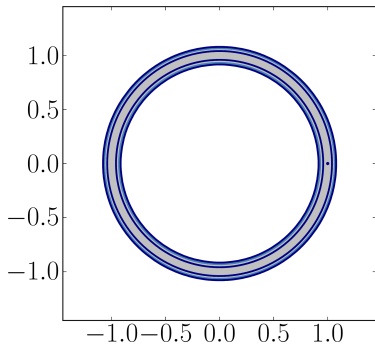
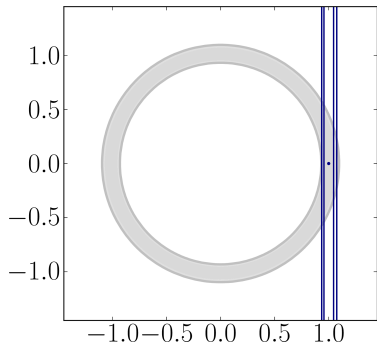
- E. Sellentin, M. Quartin, L. Amendola (2014), MNRAS, arXiv:1401.6892
- E. Sellentin (2015), MNRAS, arXiv: 1506.04866
- E. Sellentin, B.M. Schäfer, (2015), MNRAS, arXiv: 1506.05356
- C++ Code available on github

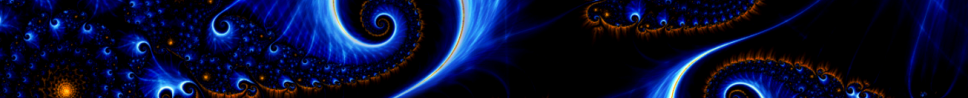
Extreme non-Gaussianities



$$C = x^2 + y^2$$

Extreme non-Gaussianities

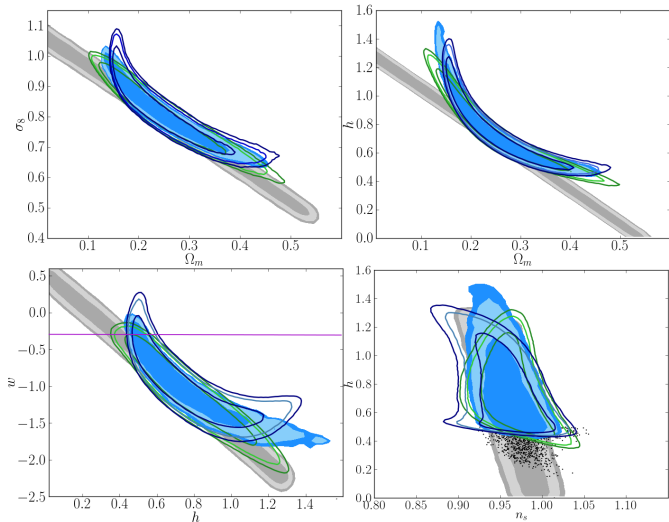




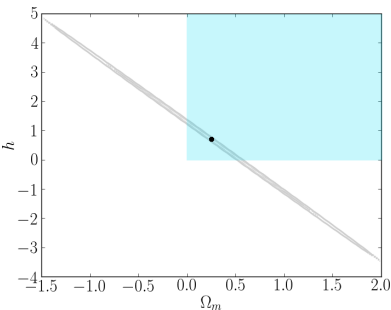
'Someone' said:
"Is just a forecasting code! Just makes shapes funnier than the
Fisher matrix."

weak lensing @ Euclid precision

Without priors!



weak lensing



What about the Cramer-Rao inequality?

$$\text{var}(\theta) \geq F_{\theta\theta}$$

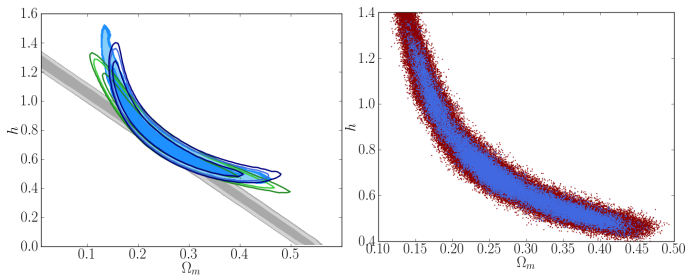
$$\text{var}(\theta) \geq F_{\theta\theta}^{-1}$$

Fisher matrix vs. Fisher information:

$$-\int f(x) \partial_{\theta} \partial_{\theta} \log [f(x)] dx = \int f(x) (\partial_{\theta} \log [f(x)])^2 dx - \int \partial_{\theta} \partial_{\theta} f(x) dx$$

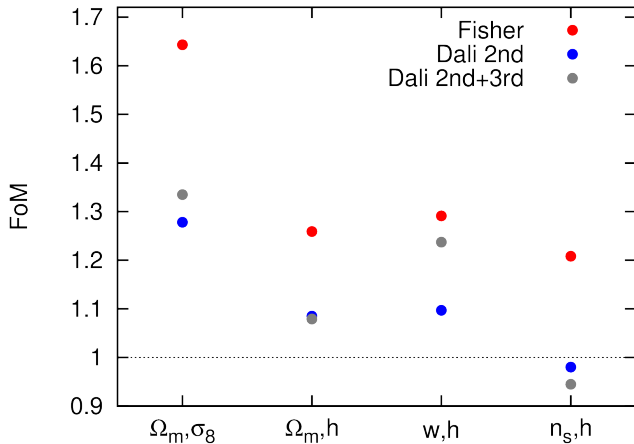
Accelerating Hamiltonian Monte Carlo

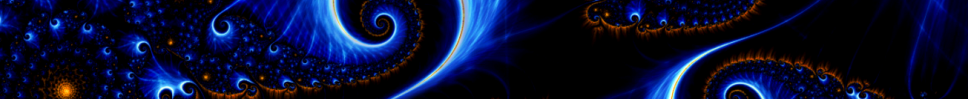
- Use \mathcal{L} as potential 'energy', add randomized kinetic energy
- Acceptance rate: 0.02 \rightarrow 0.3 – 0.5
- time/sample: $t_{leapfrog} \ll t_{MH} \rightarrow$ speed up factor depends on leap frog steps
- Works also with real data!



weak lensing

DALI is better also quantitatively:





Parameter inference with estimated covariance matrices

Estimated covariance matrices

Data from a Gaussian distribution:

$$\mathbf{X}_o \sim \mathcal{G}_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

$$L_{\mathcal{G}} = \frac{1}{\sqrt{(2\pi)^p |\boldsymbol{\Sigma}|}} \exp\left(-\frac{1}{2}(\mathbf{X}_o - \boldsymbol{\mu})\boldsymbol{\Sigma}^{-1}(\mathbf{X}_o - \boldsymbol{\mu})\right)$$

What if $\boldsymbol{\Sigma}$ cannot be calculated from first principles, but must be estimated?

$$\mathbf{S} = \frac{1}{N-1} \sum_{i=1}^N (\mathbf{X}_i - \bar{\mathbf{X}})(\mathbf{X}_i - \bar{\mathbf{X}})^T \quad (\text{for } N \rightarrow \infty \quad \mathbf{S} \rightarrow \boldsymbol{\Sigma})$$

→ Additional complications:

- \mathbf{S} is a random variable, whereas $\boldsymbol{\Sigma}$ is not
- \mathbf{S}^{-1} is biased wrt $\boldsymbol{\Sigma}^{-1}$

Estimated covariance matrices

The biased inverse:

$$\langle \mathbf{S}^{-1} \rangle = \frac{N-1}{N-p-2} \mathbf{\Sigma}^{-1} \quad (1)$$

The old recipe (Hartlap et al (2007)):

$$L_{\mathcal{G}} = \frac{1}{\sqrt{(2\pi)^p |\mathbf{S}|}} \exp\left(-\frac{1}{2}(\mathbf{X}_o - \boldsymbol{\mu}) \frac{N-p-2}{N-1} \mathbf{S}^{-1} (\mathbf{X}_o - \boldsymbol{\mu})\right)$$

Still leads to biases of the inferred *parameters*!

Estimated covariance matrices

Correctly replacing Σ by S :

$$P(X_o|\mu, S, N) = \int d\Sigma L_{\mathcal{G}}(X_o|\mu, \Sigma)P(\Sigma|S, N) \quad (2)$$

How do you get $P(\Sigma|S, N)$?

Estimated covariance matrices

Construct $P(\Sigma|\mathcal{S}, N)$:

- $\mathcal{S} = \frac{1}{N-1} \sum_{i=1}^N (\mathbf{X}_i - \bar{\mathbf{X}})(\mathbf{X}_i - \bar{\mathbf{X}})^T$ follows a Wishart distribution $\mathcal{W}(\mathcal{S}|\Sigma/(N-1), N-1)$
- Invert with Bayes' Theorem: $P(\Sigma|\mathcal{S}, N)\pi(\mathcal{S}) = \mathcal{W}(\mathcal{S}|\Sigma/n, n)\pi(\Sigma)$ by using some priors $\pi(\Sigma)$

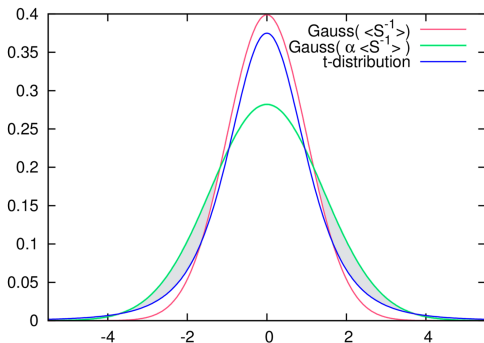
The prior discussion...

- We use an independence-Jeffreys prior $\pi(\Sigma) \propto |\Sigma|^{-\frac{p+1}{2}}$.

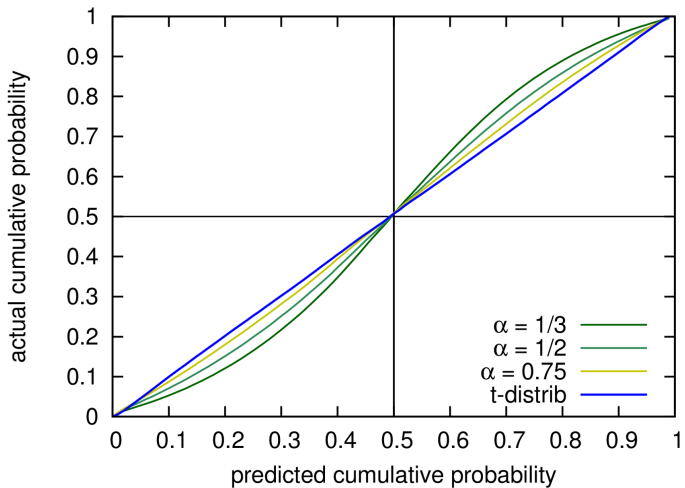
Estimated covariance matrices

Solve $P(X_o|\mu, S, N) = \int d\Sigma L_{\mathcal{G}}(X_o|\mu, \Sigma)P(\Sigma|S, N)$:

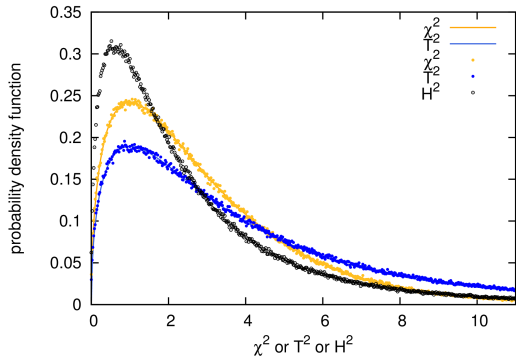
$$P(X_o|\mu, S, N) = \frac{\bar{c}_p |S|^{-1/2}}{\left[1 + \frac{(X_o - \mu)^T S^{-1} (X_o - \mu)}{N-1} \right]^{\frac{N}{2}}}$$



Estimated covariance matrices



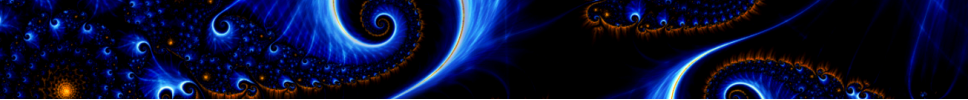
Estimated covariance matrices



$$\chi^2 = (\mathbf{X}_o - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{X}_o - \boldsymbol{\mu})$$

$$H^2 = (\mathbf{X}_o - \boldsymbol{\mu})^T \alpha \mathbf{S}^{-1} (\mathbf{X}_o - \boldsymbol{\mu})$$

$$T^2 = (\mathbf{X}_o - \boldsymbol{\mu})^T \mathbf{S}^{-1} (\mathbf{X}_o - \boldsymbol{\mu})$$



Merci :)
–End of Talk–