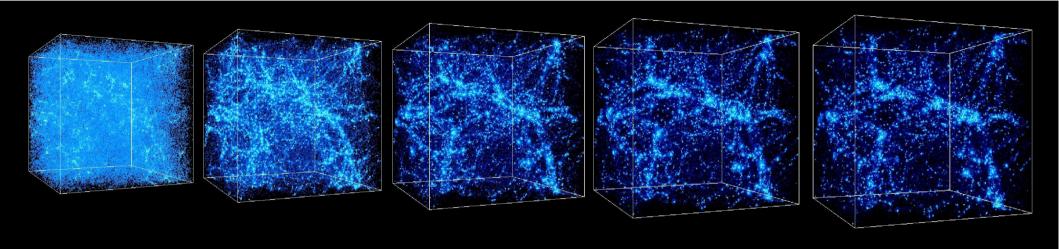
Viscous Fluids as Models for Large Scale Strcuture

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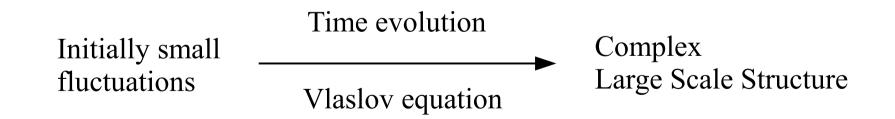
Based on

arXiv: 1509.03073 with Gerasimos Rigopoulos

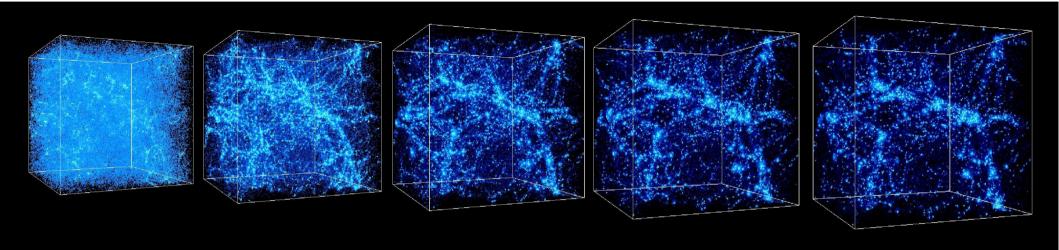
Large Scale Structure



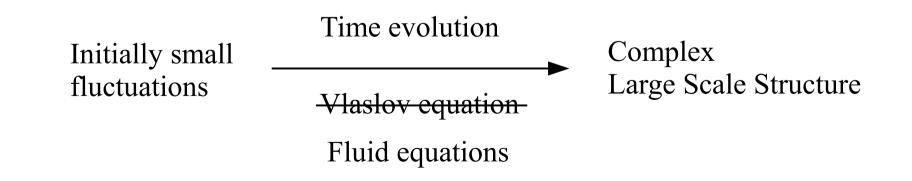
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Large Scale Structure



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Failure of Perturbation Theory

Solve fluid equation perturbatively

$$\partial_D \delta + \nabla \cdot \mathbf{w} = -\nabla \cdot (\delta \mathbf{w})$$
$$\partial_D \mathbf{w} + \frac{3}{2} \frac{\gamma}{D} \left(\mathbf{w} + \frac{\nabla \psi}{D} \right) = -\mathbf{w} \cdot \nabla \mathbf{w}$$

$$\nabla^2 \Psi = \frac{\delta}{D}$$
$$\mathbf{w} = \frac{d\mathbf{x}}{dD}$$
$$\gamma = \frac{\Omega_m}{f^2} \approx 1$$

D =growth factor

Two possible sources of failure

Soft modes: $\sigma_d^2 = \frac{4\pi}{3} \int d^3q P_L(q) \longrightarrow$ Can be resumed (RPT) Crocce, Scoccimaro 2005&2006

Gallilean invariance — Do not effect equal time correlators Scoccimaro, Frieman 1995 Kehagias, Riotto 2013 Peloso, Pietroni 2013 Blas et. al. 2013

Hard modes:
$$\sigma_l^2 = 4\pi \int d^3q \ q^2 P_L(q)$$
 \longrightarrow Strong UV-dependence

Strong dependence on modes which are

non-perturbative not described by the fluid equations

Microscopic Stress

Infinite hierarchy of moment equations $\partial_D \delta + \nabla \cdot \mathbf{w} + \nabla \cdot (\delta \mathbf{w}) = 0$ $\partial_D \mathbf{w} + \frac{3}{2} \frac{\gamma}{D} \left(\mathbf{w} + \frac{\nabla \psi}{D} \right) + \mathbf{w} \cdot \nabla \mathbf{w} = \frac{\nabla \cdot \sigma}{1 + \delta}$ $\partial_D \sigma + 3 \frac{\gamma}{D} \sigma + \mathbf{w} \cdot \nabla \sigma + \sigma \cdot \nabla + (\nabla \mathbf{w})^T \cdot \sigma = \dots$

Single stream approximation $\sigma = 0$ and all higher moments

Closed set of equation — Good approximation during early stages
 Only appears to be self-consistent — Caustics

Well defined if $\sigma \neq 0$ but, hierarchy can not be truncated

- Initial/background velocity dispersion
- Velocity dispersion is generated, when non-linear structures form

Effective Fluid for Warm Dark Matter

Stress suppresses structures at small scales $k \gg k_{\rm FS} \sim \frac{1}{\sqrt{\sigma}}$ Can construct an effective fluid description for $k \ll k_{\rm FS}$ Higher moments are of the order $\overline{w^n} \sim k_{\rm FS}^{-n}$ \longrightarrow Integrate out Split into background and perturbation $\sigma = \overline{\sigma} + \delta \sigma$ To first order in w and $k_{\rm FS}^{-1}$ the stress reads

$$\sigma \approx \sigma_i \mathbf{1} \left(\frac{D_i}{D}\right)^3 + \delta \sigma_i \left(\frac{D_i}{D}\right)^3 + \sigma_i \mathbf{1} \left(\frac{D_i}{D}\right)^3 \int_{D_i}^D d\eta \left(\nabla^2 \mathbf{w} + \nabla \nabla \cdot \mathbf{w}\right)(\eta) + \dots$$

Plug into Euler equation

$$\partial_{D}\mathbf{w} + \frac{3}{2}\frac{\gamma}{D}\left(\mathbf{w} + \frac{\nabla\psi}{D}\right) + \mathbf{w}\cdot\nabla\mathbf{w} =$$

$$= \nabla\cdot\delta\sigma_{i}\left(\frac{D_{i}}{D}\right)^{3} + \sigma_{i}\left(\frac{D_{i}}{D}\right)^{3}\nabla\delta + \sigma_{i}\left(\frac{D_{i}}{D}\right)^{3}\int_{D_{i}}^{D}d\eta \left(\nabla^{2}\mathbf{w} + \nabla\nabla\cdot\mathbf{w}\right)(\eta) + \dots$$
"Noise" Sound-speed Non-local viscosity

Effective terms are in principle known — can be ressumed FF, Yvonne Y.Y. Wong arXiv 1412.2764

Averaged Equations of Motion

Average Fields over scale
$$\Lambda^{-1}$$

 $\rho_{\Lambda}(\mathbf{x}) = \int d^3x' W_{\Lambda} \left(|\mathbf{x} - \mathbf{x}'| \right) \rho(\mathbf{x}')$
 $\rho_{\Lambda}(\mathbf{x}) \mathbf{w}_{\Lambda}(\mathbf{x}) = \int d^3x' W_{\Lambda} \left(|\mathbf{x} - \mathbf{x}'| \right) \rho(\mathbf{x}') \mathbf{w}(\mathbf{x}')$

Averaged fluid equations (index Λ dropped):

$$\partial_D \delta + \nabla \cdot \mathbf{w} + \nabla \cdot (\delta \mathbf{w}) = 0$$

$$\partial_D \mathbf{w} + \frac{\gamma}{D} \left(\mathbf{w} + \frac{\nabla \psi}{D} \right) + \mathbf{w} \cdot \nabla \mathbf{w} = \frac{\nabla \cdot \sigma}{1 + \delta}$$

Effective stress

Two possibilities

- Measure and use as a source Pietroni et. al. 2011
- Parametrize in terms of long-wavelength fields

Baumann et. al. 2012

Stochastic Fluid Equations

Effective viscous fluid with stochastic noise

 $\tau\sim \delta^{-1/2}$

$$\partial_D \mathbf{w} + \frac{3}{2} \frac{\gamma}{D} \left(\mathbf{w} + \frac{\nabla \psi}{D} \right) + \mathbf{w} \cdot \nabla \mathbf{w} = \mathbf{J} - \nu_1 \nabla \delta + \nu_2 \nabla^2 \mathbf{w} + \nu_3 \nabla \times \nabla \times \mathbf{w}$$

+higher orders

Interpreted as an effective field theory for long-wavelength perturbations

	 Higher orders suppressed by powers of √/k_* New terms constrained by symmetry Effective parameters a-priori unknown → calibrate with simulations/observations Effective parameters ensure cutoff independence → renormalization 					
k	Shell crossing		$k_{ m NL}$		H	
No flui	d description	Viscous fluid?	EFToLSS Non Loca		Relativistic	

 $\tau \sim H^{-1}?$

Non-Local in time

Backreaction

 $\tau \sim H^{-1}$

Stochastic Adhesion Model

Simplify: Neglect Vorticity $\mathbf{w} = -\nabla h$ Zel'dovich approximation $\mathbf{w} = -\frac{\nabla \Psi}{D}$

Decoupled equation: $\partial_D h + \frac{1}{2} (\nabla h)^2 = J + \nu \nabla^2 h$

. . .

EFToLSS	Viscous Fluid	
Cutoff at non-linear scale	Valid up virialization?	
Viscosity is a perturbation	Viscosity at linear order	
Non-local in time	Local in time	
Carrasco et. al. 2012 Pajer, Zaldarriaga 2013	Blas et. al. 2015	

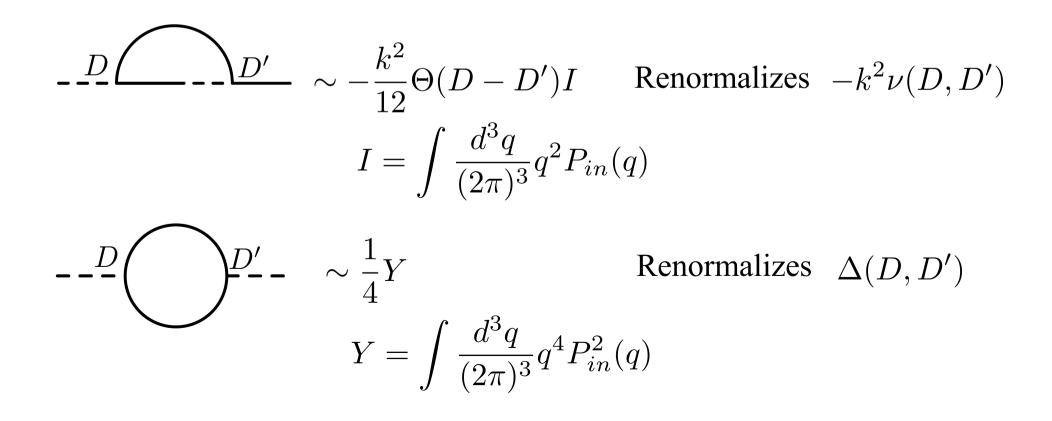
Galilean Invariance

 $h(D) \to h(D) - \partial_D \mathbf{T}(D) \cdot \mathbf{x}$ $\mathbf{x} \to \mathbf{x} + \mathbf{T}(D)$ Galilean Transformation: **Original Fluid Equations** $\partial_D + \frac{1}{2} (\nabla h) \cdot \nabla$ Covariant derivative: Galilean Invariant Gaussian Noise: $\langle J(D, \mathbf{k}) J(D', \mathbf{k}') \rangle = \Delta(D, D') \delta(\mathbf{k} + \mathbf{k}') \longrightarrow$ GI if local From momentum conversation Multiplicative noise A non-local noise must be of the form $J(\mathbf{x}_{fl}) = J(\mathbf{x}) + \int_0^D d\eta \, (\nabla h)(\mathbf{x}) \cdot \nabla J(\mathbf{x}) + \dots$ Non-local correlators With $\mathbf{x}_{fl}(D) = \mathbf{x} + \int_{D_{in}}^{D} d\eta \, \nabla h(\mathbf{x}_{fl}(\eta), \eta)$ Viscosity: ∇h is not invariant \rightarrow Build higher order operators from $\nabla^2 h$ $\int_{0}^{D} dD' \,\nu(D,D') \nabla^{2} h(D',\mathbf{x}_{fl}(D')) = \int_{0}^{D} dD' \,\nu(D,D') \nabla^{2} h(D',\mathbf{x}(D'))$ Non-local viscosity + $\int_{\Omega}^{D} dD \int_{\Omega}^{D'} d\eta \,\nu(D,D') \nabla^2 \left((\nabla h(x,\eta)) \cdot \nabla h(D',\mathbf{x}) \right) + \dots$ New vertex

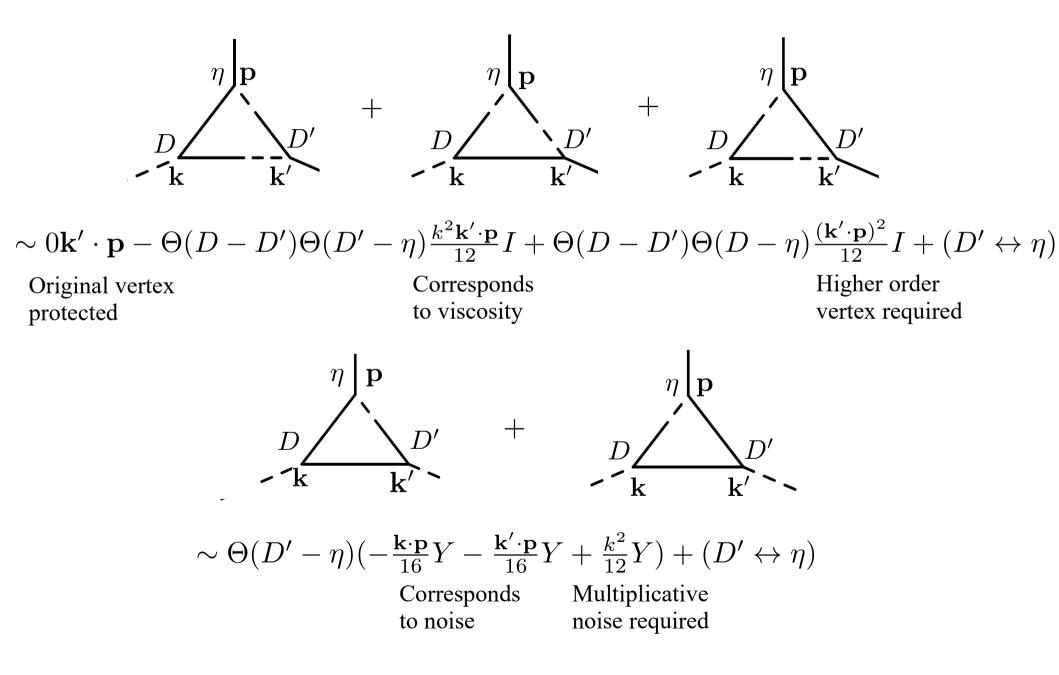
Effective Filed Theory of Large Scale Structure

EFToLSS: SPT + perturbative corrections from ν and J

PropagatorLinear Power SpectrumVertex $g(D, D') = \Theta(D - D')$ $P(k, D, D') = P_{in}(k)$ $\gamma(\mathbf{k}_1, \mathbf{k}_2) = \frac{\mathbf{k}_1 \cdot \mathbf{k}_2}{2}$



Effective Filed Theory of Large Scale Structure



Viscous Fluid

Non-perturbative treatment of effective terms

Assume gaussian noise $\langle J(D,k)J(D',k')\rangle = \Delta \tilde{\nu}^3(D)\delta_D(D-D')\delta_D(\mathbf{k}+\mathbf{k}')$

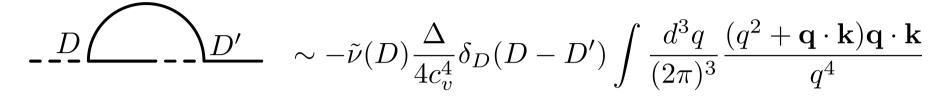
Propagator: $g_k(D,D') = exp\left(-c_v^2 k^2 \int_{D'}^D d\eta \,\tilde{\nu}(\eta)\right) \Theta(D-D')$

Linear Power spectrum:
$$P(k, D, D') = P_{in}(k)g_k(D, 0)g_k(D', 0)$$
$$+\Delta \int_0^{\min(D, D')} d\eta \ g_k(D, \eta)g_k(D', \eta)\nu^3(\eta)$$

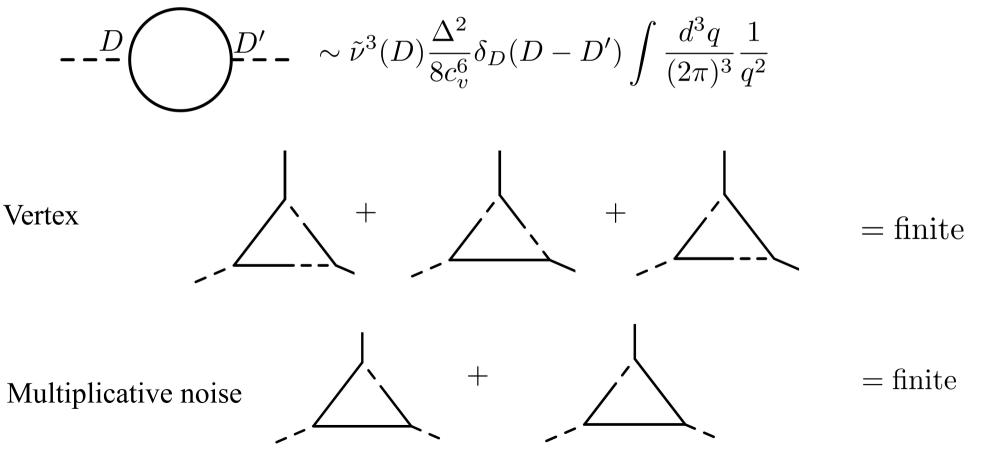
Asymptotic behavior:

Viscous Fluid Renormalization

Viscosity



Noise



Ward-Identities

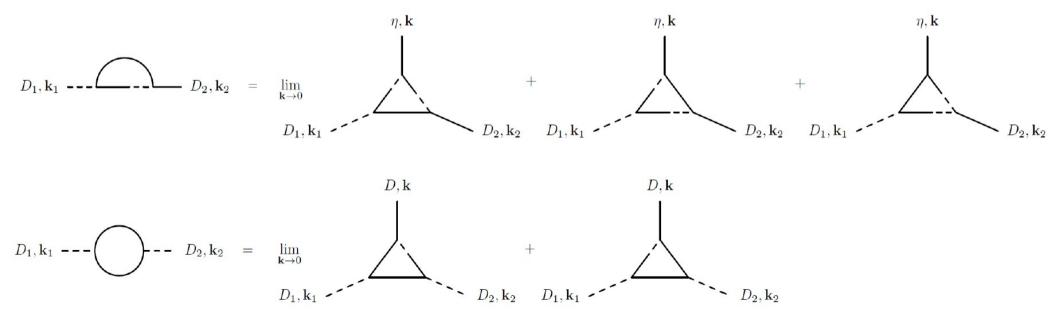
Written in terms of 1PI-vertices the Ward-Identities read, for $n \neq 1$ $m \neq 0$

$$\sum_{i=1}^{n} \mathbf{p}_{i} \delta_{D} (D - \eta_{i}) \Gamma^{(n,m)} + \sum_{i=1}^{m} \mathbf{q}_{i} \delta_{D} (D - \lambda_{i}) \Gamma^{(n,m)} = \int d^{3}k \, \delta_{D}(\mathbf{k}) \partial_{D} \partial_{\mathbf{k}} \Gamma^{(n,m+1)}$$

Kehagias, Riotto 2013

Kehagias, Riotto 2013 Peloso, Pietroni 2014 Frey, Täuber et. al 1994

At one loop



Ward-Identities

At one loop the WI can be written as

$$\Sigma (D_1, D_2; k_1) \mathbf{k}_1 (\theta (\eta - D_1) - \theta (\eta - D_2)) = \lim_{\mathbf{k} \to 0} \partial_{\mathbf{k}} \Pi (D_1, D_2, \eta; \mathbf{k}_1, \mathbf{k})$$

 $\Phi\left(D_{1}, D_{2}; k_{1}\right) \mathbf{k}_{1}\left(\theta\left(\eta - D_{1}\right) - \theta\left(\eta - D_{2}\right)\right) = \lim_{\mathbf{k} \to 0} \partial_{\mathbf{k}} \Psi\left(D_{1}, D_{2}, \eta; \mathbf{k}_{1}, \mathbf{k}\right)$

In the limit $\mathbf{k} \to 0$ $\Pi = \mathbf{k} \cdot \mathbf{k}_1 \tilde{\Pi}(k_1) \quad \Psi = \mathbf{k} \cdot \mathbf{k}_1 \tilde{\Psi}(k_1)$

Plugging in

 $\Pi \left(D_1, D_2, \eta; \mathbf{k}_1, \mathbf{k} \right) = \mathbf{k}_1 \cdot \mathbf{k} \Sigma \left(D_1, D_2; k_1 \right) \left(\theta \left(\eta - D_1 \right) - \theta \left(\eta - D_2 \right) \right) + O(k^2)$

 $\Psi(D_1, D_2, \eta; \mathbf{k}_1, \mathbf{k}) = \mathbf{k}_1 \cdot \mathbf{k} \Phi(D_1, D_2; k_1) \left(\theta(\eta - D_1) - \theta(\eta - D_2)\right) + O(k^2)$

Non-Local: Divergences appears in higher vertices again

Local: Vertices protected

Comparison

Neglect the noise and assume a numerical small velocity

Choose
$$\nu(D) = c_v^2 D$$

 $B_{EFT/Fluid} = B_{tree} + B_{1-loop} + gD_3^3 \frac{(\mathbf{k}_1 \cdot \mathbf{k}_2)^2}{6} P_{in}(k_1) P_{in}(k_2)$
 $-c_v^2 \frac{\mathbf{k}_1 \cdot \mathbf{k}_2}{2} P_{in}(k_1) P_{in}(k_2) \left(\frac{k_1^2}{6}(D_3^2 + 3D_2^2D_3) + \frac{k_2^2}{6}(D_3^2 + 3D_1^2D_3) + k_3^2 D_3^3 \left(\frac{1}{2} - \frac{1}{6}\right)\right) + permutations$

 c_v Fixed by 1-loop Power Spectrum \rightarrow Difference from extra vertex and integrals $\int dDDD^n \neq \int dD \int dDD^n$ g Needs to be fixed by 2-loop Power Spectrum

EFT seems to prefer a local viscosity

Foreman, Senatore 2015 Carrasco et. al 2014

Conclusion and Outlook

- Counter terms in EFToLSS necessarily non-local
 - New vertices at higher order
 - WI guarantees that renormalization is possible
- Local Viscosity possible
- Local and Non-local viscosity differ on large scales
- Relation to the approach of Blas et. al.?
- Is the noise important?
 - Can the noise reproduce the PS at small scales
- Derive from UV-completion