

13 Calabi-Yau compactifications

13.1 Compactifications

- Assume background to respect 4d Poincare symm.
Most general metric:

$$G_{MN}(x,y) = \begin{pmatrix} f(y)\eta_{\mu\nu} & \\ & G_{mn}(y) \end{pmatrix}$$

$x^M = (x^0 \dots x^3)$ $y^m = (y^4 \dots y^9)$

- Topology: $\mathcal{M} = \mathbb{R}^4 \times_w K^6 \leftarrow$ compact 6d manifold
to remind us of the "warped" metric ansatz
- Focus on $f(y) = 1$ and $\mathcal{M} = \mathbb{R}^4 \times K^6$ (non-warped case)
- For a scalar field φ :

$$\mathcal{L} \supset \varphi \mathcal{D}^M \partial_M \varphi \equiv \varphi \Delta_{10} \varphi = \varphi \Delta_4 \varphi + \varphi \Delta_6 \varphi$$

- Let $\varphi = \sum_n \varphi_n(x) \underbrace{\tilde{\varphi}_n(y)}_{\text{eigenfunctions of } \Delta_6}$

(e.g., for $K^6 = T^6$, $n = (n^1, \dots, n^6)$ and

$$\tilde{\varphi}_n = \exp \left[\sum_{m=4}^9 \frac{n^m y^m}{R_m} \right] \text{ with } \{R_m\} \text{ a set of radii}$$

- $S_{4d, \text{eff}} = \text{Vol}(K^6) \int d^4x \sum_n \varphi_n(x) \left(\partial_\mu \partial^\mu - m_n^2 \right) \varphi_n(x)$
 set of 4d fields (in our example: $= \sum_{m=4}^9 \left(\frac{n^m}{R_m} \right)^2$)
 (Kaluza-Klein-modes)

- Most important for us: 4d fields with $m_n = 0$
($\hat{=}$ zero modes of Δ_6)

- Simplest case: $\mathbb{R}^4 \times \mathcal{K}^6$ solves EOMs with all background fields [except dilaton ($\varphi = \text{const}$) and metric (see above)] set to zero.

- $T_{MN} = 0 \implies R_{MN} = 0 \implies R_{mn} = 0$
 (Einstein eq.) ("Ricci flatness")

- It is convenient (though not strictly necessary) to insist on one surviving SUSY ($N=1$ SUSY in 4d).

- Recall: $\delta_\epsilon \psi_m = \nabla_m \epsilon + \text{field-dependent terms}$
 (generically present in 10d SUGRAs)
 in general: Maj.-Weyl spinor in $d=10$

- Our vacuum should be invariant under (at least) one specific $\epsilon = \epsilon(\gamma)$.

- Note: ϵ is (locally) from the 16 of $SO(1,9)$

$$SO(1,9) \supset SO(1,3) \times SO(6) \quad (\text{use } SO(6) \cong SU(4))$$

$$16 = (2, 4) + (\bar{2}, \bar{4})$$

because of the Majorana constraint, this will be fixed by the $(2, 4)$ -part

- 16 SUSY generators in 10d \implies maximum of 4×4 SUSY generators in 4d
 $\uparrow \quad \uparrow$
 $(2, 4)$
 compl. Weyl spinor \nwarrow 4 copies thereof

- We want one of these 4 4d- $N=1$ -SUSYs to survive

- For this, we need only one solution to $\nabla_m \epsilon(\gamma) = 0$
 (The 3 other real generators will be guaranteed by $SO(1,3)$ -symm.)

- Write $\epsilon_{10d}(y) = \epsilon_{4d} \times \epsilon_{6d}(y)$ with $\nabla_m \epsilon_{6d}(y) = 0$
(our manifold should have a covariantly constant spinor)

- This implies: $[\nabla_m, \nabla_n] \epsilon_{6d}(y) = \frac{1}{4} R_{mnpq} \Gamma^{pq} \epsilon_{6d}(y) = 0$

This infinitesimal $SO(6)$ rotation should leave one spinor invariant. (This extends to finite parallel transports along the whole manifold.)



all such parallel transports should leave one spinor (one direction of the 4 of $SU(4)$) invariant.

\Rightarrow The holonomy is reduced from $SO(6) = SU(4)$ (the generic case) to $SU(3)$.

[$SU(4)$ matrix $\stackrel{!}{=} \left(\begin{array}{c|c} SU(3)\text{-matrix} & \\ \hline & 1 \end{array} \right)$ which, applied to $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$, acts trivially.]

Thus: We are looking for Ricci-flat manifolds with a covariantly constant spinor (or $SU(3)$ holonomy).

13.2 Calabi-Yau manifolds

General setting:

- Consider 3d-complex (rather than 6d real) manifolds.
(An even-dim. real manifold is complex if the transition fcts. are holomorphic.)

- Generic metric: $ds^2 = 2G_{i\bar{j}} dz^i d\bar{z}^{\bar{j}} + \underbrace{G_{ij} dz^i dz^j + G_{\bar{i}\bar{j}} d\bar{z}^{\bar{i}} d\bar{z}^{\bar{j}}}_{\text{if these vanish, } G \text{ is called hermitian.}}$

- A subclass of hermitian metrics are Kähler metrics:

$G_{i\bar{j}}$ can be locally written as $G_{i\bar{j}} = \frac{\partial}{\partial z^i} \frac{\partial}{\partial \bar{z}^{\bar{j}}} K(z, \bar{z})$
 "Kähler potential"

- Important for us: There exist many compact Kähler manifolds.

- Naive attempt: polynomial constraints in \mathbb{C}^n

(e.g. \mathbb{C}^2 parameterized by (z^1, z^2) ; $K = z^1 \bar{z}^1 + z^2 \bar{z}^2$;
 submanifold defined by $(z^1)^2 + (z^2)^2 = 1$; ...
 ... easy to generalize to $n \geq 3$ and constraints making the submanifold 3-dimensional)

- Problem: All such submanifolds are non-compact!

- Better: Start with complex projective spaces \mathbb{P}^n instead of \mathbb{C}^n . (\mathbb{P}^n is the set of all vectors (z^0, \dots, z^n) with $(z^0, \dots, z^n) \sim (\lambda z^0, \dots, \lambda z^n)$.)
 equivalence relation

The \mathbb{P}^n are compact and have a natural Kähler metric. (other notation: $\mathbb{C}\mathbb{P}^n$)

(in the patch where $z^j \neq 0$ choose coords. $\vartheta^i = \frac{z^i}{z^j}$ ($i \neq j$)
 & $K = \ln(1 + \sum_{i \neq j} |\vartheta^i|^2)$ (\Rightarrow "Fubini-Study-metric"))

Theorem: (Yau, conjectured by Calabi)

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Given a Kähler manifold satisfying a certain topological restriction (vanishing 1st Chern class, $c_1 = 0$), then the Kähler metric can be deformed to a unique Ricci-flat metric (within a certain "Kähler class" (see below)).

\Rightarrow Calabi-Yau manifolds (SU_3 holonomy & covar. constant spinor are then guaranteed.)

Fact: There exists a large class of submanifolds of \mathbb{P}^n (and of products $\mathbb{P}^n \times \mathbb{P}^m \times \dots$), defined by polynomial constraints, which have $c_1 = 0$ and thus provide examples of CY-manifolds. "Complex Intersection CYs"
(Although the Ricci-flat metric can, unfortunately, not be explicitly constructed, a lot is known about these spaces & the corresp. string-th. compactifications.)

Simplest example: Quintic in \mathbb{P}^4 : Submanif. of \mathbb{P}^4 defined by $\underbrace{c_{i_1 \dots i_5}} z^{i_1} \dots z^{i_5} = 0$.

smoothly varying these coeff.-s. corr. to deforming the submanifold.

• To understand $c_1 = 0$ better, we need some more technology:

1) de Rham cohomology:

$$\omega_p \begin{cases} \text{closed} : d\omega_p = 0 & \text{exact} \Rightarrow \text{closed} \\ \text{exact} : \omega_p = d\alpha_{p-1} & \text{(since } d^2 = 0 \text{)} \end{cases}$$

- p th de Rham cohomology of K :

$$H^p(K) = \frac{\text{closed } p\text{-forms on } K}{\text{exact } p\text{-forms on } K} \quad ; \quad \text{Betti number: } b_p = \dim(H^p(K))$$

(\equiv lin. space of equivalence classes of closed forms;

$$\omega_p \sim \omega_p' \text{ if } \exists \text{ exact } \omega_p'' \text{ such that } \omega_p = \omega_p' + \omega_p'')$$

- example: $- H^0(S^1) = \frac{\{\text{const. fctrs.}\}}{\{0\}} = \text{const. fctrs.} \cong \mathbb{R}$

(b_0 simply counts connected components)

$$- H^1(S^1) = \frac{\{\text{all 1-forms}\}}{\{1\text{-forms } f_1 dx^1 = (\partial_1 f) \cdot dx^1\}} \cong \mathbb{R}$$

(Locally, any f_1 can be written as $\partial_1 f$. Globally, this can fail if $\int_0^{2\pi} f_1 \cdot dx^1 = c \neq 0$. The constant c parameterizes the above equiv. classes. Thus $b_1(S^1) = 1$ is related to the presence of a non-contractible loop.)

$$- H^2(S^1) = 0 \text{ by dimensionality.}$$

2) Dolbeault cohomology:

- in the complex case: $d = \partial + \bar{\partial}$ with $\partial = dz^i \partial_i$

$$\partial^2 = \bar{\partial}^2 = 0$$

$$\& \bar{\partial} = d\bar{z}^{\bar{i}} \partial_{\bar{i}}$$

- using the concept of (p, q) -forms ($\omega_{p,q} = (\omega_{p,q})_{i_1 \dots i_p, \bar{i}_1 \dots \bar{i}_q}$

define

$$H_{\bar{\partial}}^{p,q}(K) = \frac{\bar{\partial}\text{-closed } (p,q)\text{-forms}}{\bar{\partial}\text{-exact } (p,q)\text{-forms}}$$

$$\cdot dz^{i_1} \dots dz^{i_p} d\bar{z}^{\bar{i}_1} \dots d\bar{z}^{\bar{i}_q}$$

- For Kähler manifolds $H_{\mathbb{R}}^{p,q} = H_{\mathbb{C}}^{p,q} \cong H^{p,q}$

$$\dim(H^{p,q}) = h^{p,q} \text{ (Hodge numbers)}$$

Back to our main interest: CYs

- Kähler metric \Rightarrow Ricci tensor has only non-zero components of type $R_{i\bar{j}}$.
- Ricci-form: $R_{1,1} = R_{i\bar{j}} dz^i d\bar{z}^{\bar{j}}$; $dR_{1,1} = 0$
- $R_{1,1}/(2\pi)$ defines element in $H^{1,1}$. This element is the 1st Chern class c_1 . $c_1 = 0$ means $R_{1,1}$ is exact.
- (Conditions on constraint polynomials in products of \mathbb{P}^n are known which ensure $c_1 = 0$.)
- Furthermore, for a CY-3-fold:

$$\begin{array}{cccc}
 & & h^{3,3} & \\
 & & h^{3,2} & h^{2,3} \\
 & h^{3,1} & h^{2,2} & h^{1,3} \\
 h^{3,0} & h^{2,1} & h^{1,2} & h^{0,3} \\
 & h^{2,0} & h^{1,1} & h^{0,2} \\
 & h^{1,0} & h^{0,1} & \\
 & h^{0,0} & &
 \end{array}
 =
 \begin{array}{cccc}
 & & & 1 \\
 & & 0 & 0 \\
 & 0 & h^{1,1} & 0 \\
 1 & h^{2,1} & h^{2,1} & 0 \\
 & 0 & h^{1,1} & 0 \\
 & 0 & 0 & \\
 & & & 1
 \end{array}$$

} By symm.

$$(\text{Euler } \# : \chi = 2(h^{1,1} - h^{2,1}))$$

- particularly important entries:
 - volume form; unique holom. 3-form Ω (with $\bar{\Omega}$);
 - $h^{1,1} > 0$ (since metric-form $\in H^{1,1}$)

- A cohomology class H^p contains closed forms ω_p differing by exact forms.
- Demanding $d^* \omega_p = 0$ (in addition to $d\omega_p = 0$) one finds a unique harmonic form ω_p in each H^p
($\Delta \omega_p = (d + *d^*)^2 \omega_p = 0$)
- This carries over to the Dolbeault-cohomology of Kähler manifolds.
- A metric fluctuation $G_{i\bar{j}} \rightarrow G_{i\bar{j}} + g_{i\bar{j}}$ can be described by a (1,1)-form $g = g_{i\bar{j}} dz^i d\bar{z}^{\bar{j}}$. It is massless if $\Delta g = 0 \Rightarrow h^{1,1}$ counts # of these "Kähler moduli".
($G_{i\bar{j}} dz^i d\bar{z}^{\bar{j}} \in H^{1,1}$ specifies the Kähler class, which is changed by this fluctuation.)
- A metric fluctuation $G_{i\bar{j}} = 0 \rightarrow G_{i\bar{j}} = 0 + g_{i\bar{j}}$ can be described by a (1,2)-form $\omega_{i\bar{j}\bar{k}} = g_{i\bar{j}} G^{j\bar{k}} \Omega_{\bar{k}\bar{l}\bar{m}}$. It is massless if $\Delta \omega = 0 \Rightarrow h^{1,2}$ counts # of "complex structure moduli".
(After the metric is modified by $g_{i\bar{j}}$, the "complex structure" has to be changed to make the manifold again "Kähler".)
- So far, we have been discussing generic CY-compactifications (this is relevant for all 10d superstring theories).
- more specifically: heterotic case:
 $\tilde{H}_3 = 0 \Rightarrow$ SU(2) EDMs require $\text{tr}(R_2 \wedge R_2) - \text{tr}(F_2 \wedge F_2) = 0$

- simplest solution: Identify gauge connection ($SU_3 \subset E_8$) with spin connection ($SU_3 \subset SO_6$)
- use the "standard embedding" of SU_3 in E_8 :

$$E_8 \supset E_6 \times SU_3 \text{ (max. rank subgroup)}$$
- One finds fields charged under the "surviving" 4d gauge group E_6 :
 - $h^{2,1}$ chiral superfields (in particular 4d Weyl fermions) in 27 of E_6
 - $h^{1,1}$ chiral superfields in $\bar{27}$ of E_6
- Note: $E_6 \supset SO_{10} \supset SU_3 \times SU_2 \times U_1$

$$27 = \begin{matrix} 15 \\ +10 \\ +1 \end{matrix} = \text{one complete family (incl. singlet } \nu \text{) of the standard model}$$
- \Rightarrow # of families: $h^{2,1} - h^{1,1} \equiv -\frac{\chi}{2}$ Euler #.
- for recent work on models of this type (in fact, much more involved...) \rightarrow B. Ovrut et al.