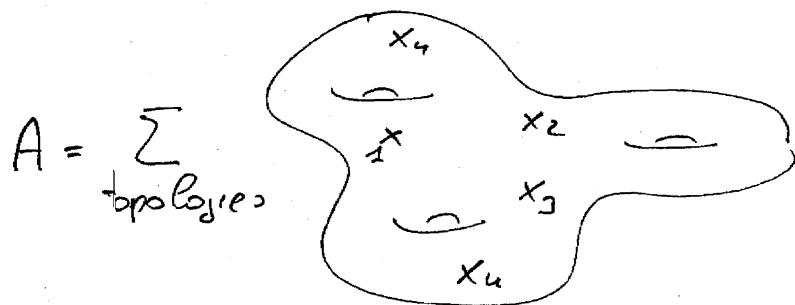


String Amplitudes

The interaction of n incoming/outgoing states can be written as



$$A = \sum_{\text{topologies}}$$

$$= \sum_{\text{topologies}} \frac{\int [dx][dg]}{V_{\text{diff}} \times \text{Weyl}} e^{-S_x} v_1 \dots v_n$$

where the denominator $V_{\text{diff}} \times \text{Weyl}$ keeps into account the gauge invariance that must be modded out, and v_i is the vertex operator of the i -th outgoing state.

We can avoid the denominator and properly quantize the theory by using the Faddeev Popov approach.

Given a "preferred" metric \hat{g} (flat metric) we know that there exists always a transformation $\Xi \in \text{Diff} \times \text{Weyl}$ such that, for each possible metric g , $g = \hat{g}\Xi = \Xi(\hat{g})$ locally.

This allows us to write

$$1 = \Delta_{FP}(g) \int d\Xi S(g - \hat{g}\Xi)$$

and to replace it into the amplitude

$$A|_{\substack{\text{given} \\ \text{topology}}} = \frac{\int [dx dg d\Xi]}{V_{\text{diff}} \times \text{Weyl}} S(g - \hat{g}\Xi) e^{-S_x} v_i - v_n \Delta_{FP}(g)$$

We can then integrate w.r.t. ξ

$$A_{g.t.} = \int \frac{[dx d\xi]}{V_{\text{diff. Weyl}}} e^{-S_x[\hat{f}\xi]} \quad V_i - V_u \Delta_{\text{FP}}(\hat{f}\xi)$$

moreover, since S_x is ξ -invariant, and
so is Δ_{FP} (check)

$$A_{g.t.} = \int [dx] e^{-S_x[\hat{f}]} V_i - V_u \Delta_{\text{FP}}(\hat{f}) \\ \times \underbrace{\int \frac{d\xi}{V_{\text{diff. Weyl}}}}_{=1}$$

Subtleties In order that the "change" of
variable $df = d\xi (\frac{\partial f}{\partial \xi})$, of which
 $\frac{\partial f}{\partial \xi} \sim \Delta_{\text{FP}}$, be well defined we need a
one-to-one map, i.e.

$\forall f \exists ! \xi \mid \hat{f}\xi = f$ globally

1) Local \rightarrow Global

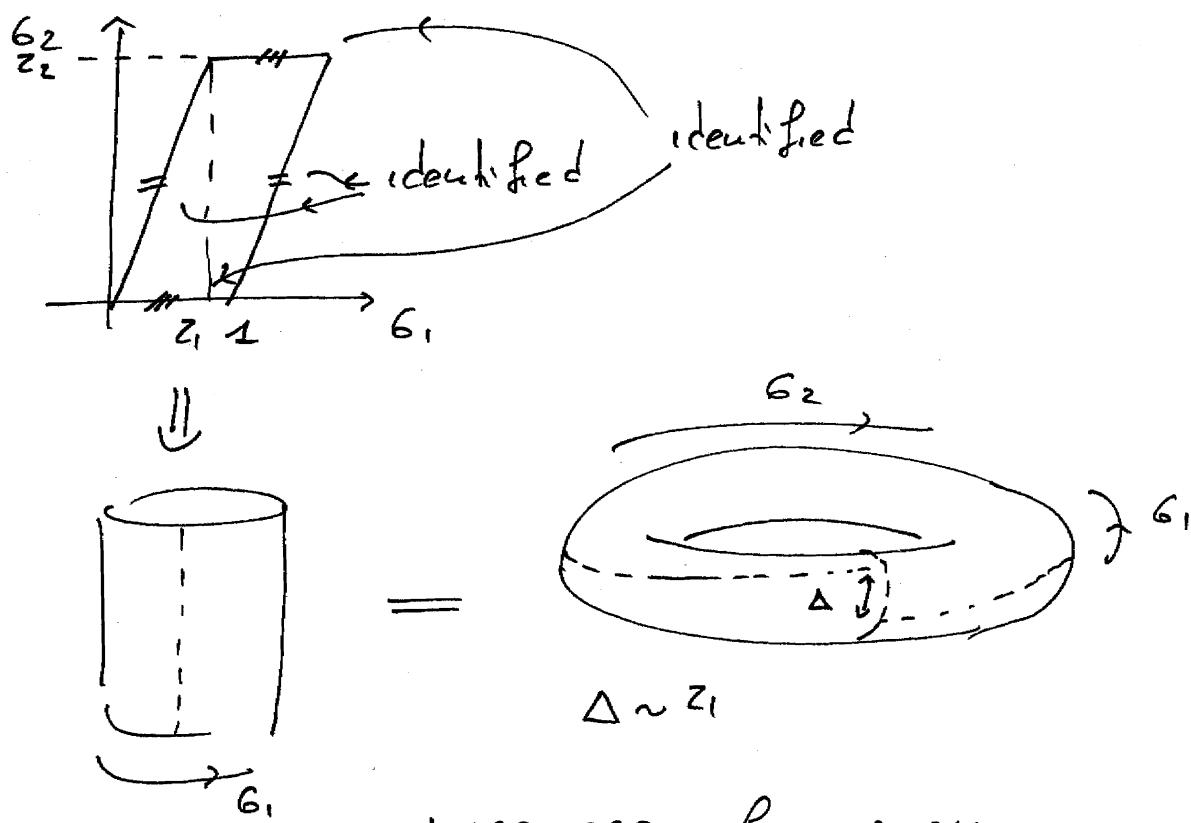
$$\Rightarrow \exists \text{ in general } g, g' \mid \\ \not\exists \xi \mid g\xi = g'$$

2) Ξ^P_0 $\Rightarrow \exists \text{ in general } \xi \mid g\xi = f$

ξ is called conformal killing vector
and is perp to the \sim group chs

Torus case

(1) It is always possible to bring g to $g_{\text{can}} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ via Diff \times Weyl
but the boundary conditions are then non-trivial



more precisely, choose

$$z = g_1 + i g_2$$

$$z \sim z + (m + n z)$$

and the statement is that it is not possible to reobtain z via Diff \times Weyl without modification

$$y_{ab} \rightarrow f_{ab}(z)$$

Choice

Tolle trivial b.c.

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$$\Rightarrow (G_1, G_2) \sim (G + u + z_1 n, G_2 + z_2 u)$$

$$\text{Let } G_1' = G_1 - G_2 \frac{z_1}{z_2}$$

$$G_2' = \frac{G_2}{z_2}$$

$$(G_1', G_2') \sim (G_1' + u + z_1 n - z_2 u, G_2' + u)$$

\Rightarrow c.v.d

but

$$ds^2 = d\sigma^2 + dG_2^2 = |dG_1' + dG_2' z|^2$$

$$= g_{ab} dG^a dG^b \quad g = \begin{pmatrix} 1 & z_1 \\ z_1 & |z|^2 \end{pmatrix}$$

Consequence

A single fiducial metric \hat{g} is no more sufficient since $O\hat{g} = \{\hat{g}^\varepsilon, \varepsilon \in \text{diff-vec}\}$
 $O\hat{g} \neq \text{set of all metrics}$

Statement $\hat{g}(z)$ is indeed sufficient

$$\int dz \ O\hat{g}(z) = \text{set of all metrics}$$

Theorem Rep. here $I = \Delta_{FP}(g) \int dz \delta(g - \hat{g}^\varepsilon)$

with

$$I = \Delta_{FP}(g) \int dz \delta(g - \hat{g}^\varepsilon(z))$$

Generalization

To us \rightarrow a single complex
Teichmüller moduli

Other manifolds \rightarrow the real

$$I = \Delta_{FP}(g) \int_{i=1}^{n_e} dt' \delta(g - \hat{g}^\varepsilon(t'))$$

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(2) $\exists: G^0 \rightarrow G^0 + Q^0$
 is a perfectly well-defined Diff transformation
 but $\exists: Y_{\mu\nu} \mapsto Y_{\mu\nu}$

Statement: on the torus only these two transformations, parametrized by Q^1 and Q^2 , defines the continuous part of the CKG

Solution: insert Q^0 -dependence in Δ_{FP}

$$1 = \Delta_{FP}(G, g) \prod_{i=1}^n \int dt^i \int d\tilde{z} \delta(g - \hat{g}^i(z^i)) \delta(G_i - \hat{G}_i(z^i)) \times \\ \times \delta(G_2 - \hat{G}_2(z^2))$$

The problem is solved since, given

$$\hat{\sum} | g = \hat{g}^i, \exists \forall z^i_{cnc} | G = \hat{G}^i z^i_{cnc}$$

Generalization

It is possible to reabsorb the ambiguity of a CKG of real dimension n_K by introducing n_K Dirac deltas

$$\delta(G_i - \hat{G}_i(z^i))$$

in the definition of Δ_{FP}

$$1 = \Delta_{FP}(G_i, g) \prod_{i=1}^{n_K} \int_{F_i} dt^i \int d\tilde{z} \delta(g - \hat{g}^i) \prod_{i=1}^{n_K} \delta(G_i - \hat{G}_i(z^i))$$

Integration region for the moduli

\Rightarrow To two case

In principle $F \subset \mathbb{R}^2$, let's see the details

take the parametrization

$$(G_1, G_2) \sim (G_1 + m + z_1 u, G_2 + z_2 u)$$

$$ds^2 = dG_1^2 + dG_2^2$$

$$\text{def } \omega = G_1 + i G_2$$

$$\Rightarrow ds^2 = d\omega d\bar{\omega}$$

$$\omega \sim \omega + m + zu$$

Now (1) replace z with z_{+1} (T)

$$\Rightarrow \text{some b.c. in } m' = m + u, n' = u$$

(2) replace z with $-1/z$ (S)

$$\omega \sim \omega + m - \frac{n}{z}$$

$$\text{redefine } \omega' = z\omega$$

$$\Rightarrow \omega' \sim \omega' + m z - n \Rightarrow \text{same as before}$$

$$(ds^2 = d\omega' d\bar{\omega}' \text{ via work with})$$

$$\Rightarrow F = \mathbb{R}^2 /$$

Grp Generated by T and S

Statement ① T, S generate (span)

$SL(2, \mathbb{Z})$ of transformations

$$z' = \frac{az+b}{cz+d} \quad a, b, c, d \in \mathbb{Z} \quad ad - bc = 1$$

$$\textcircled{2} \quad F \Rightarrow \text{Re } z \in [-\epsilon, \epsilon]$$

$$|z| > 1 \quad (\mathbb{R}, > 0)$$

$$1 = \Delta_{FP}^{\text{ue}}(g, G) \stackrel{\text{ue}}{\prod}_{i=1}^n \int dt \int d\zeta \delta(g - \hat{g}(t)^{\zeta}) \prod_{a=1}^m \delta(G^a - \hat{G}^a(\zeta))$$

$$\Delta_{FP}^{-1}(g, G) = \prod_{i=1}^n \int dt \int d\zeta \delta(g - \hat{g}(t)^{\zeta}) \prod_{a=1}^m \delta(G^a - \hat{G}^a(\zeta))$$

now \exists ! zero but (lost subtlety)

notice that we fixed all continuous symmetries, \exists a lost discrete symmetry

TORSI $G \rightarrow -G$

To fix it is enough to remember that there are $n_R=2$ zeros, and to expand around just one of them

$$\Delta_{FP}^{-1}(g, G) = n_R \prod_{i=1}^n \int dt \int d\zeta \delta(g - \hat{g}(t)^{\zeta}) \prod_{a=1}^m \delta(G^a - \hat{G}^a(\zeta))$$

$$d\zeta = dw d\epsilon$$

$$g - \hat{g}(t)^{\zeta} = \left. \delta g \right|_{\sim \text{zero}} = (2w - P_c e^c) \hat{g}_{ab} - (P_a e_b + P_b e_a - P_c e^c) \hat{g}_{ab}$$

$$+ t^i \partial_t^i \hat{g}_{ab}$$

$$\Delta_{FP}^{-1}(g, G) = n_R \prod_{i=1}^n \int dt \int dw d\epsilon \delta((2w - P_c e^c) \hat{g}_{ab} - 2P_e e_{ab} + t^i \partial_t^i \hat{g}_{ab}) \prod_{a=1}^m \delta(\epsilon^a) \Leftarrow \text{Specific Poisson Tors}$$

exponentiate the δ^a

$$\Delta_{FP}^{-1}(\hat{g}, \hat{G}) = n_R \prod_{i=1}^n \int dt \int dw d\epsilon^a d\beta^{ab} dx_a$$

$$\exp \left\{ \bar{z}^a i \int d^2 \zeta \sqrt{g} \beta^{ab} [(2w - P_c e^c) \hat{g}_{ab} + 2P_e e_{ab} + t^i \partial_t^i \hat{g}_{ab}] \right\}$$

$$\exp \left\{ z \bar{z} i \epsilon^a x_a \right\}$$

Integrate $d\omega \rightarrow \beta^{\text{obs}} \text{ tracer} \quad (\beta^{\text{obs}} = \infty)$

$$\Delta_{FP}^{-1}(\hat{g}, \hat{G}) = n_R \frac{u}{\pi} \int dt \int d\epsilon^\alpha d\beta^{\text{obs}} dx_\alpha$$

$$\exp \left\{ 2\pi i \int d\epsilon^\alpha \bar{\Gamma}_{\hat{g}} \beta^{\text{obs}} (2P\phi)_{\alpha\beta} - t^i \delta_{i\beta} \right\}$$
$$\exp \{ 2\pi i \epsilon \cdot x \}$$

\rightarrow It is just a determinant of a new modified operator

\Rightarrow Pass to Grassmann variables to "insert"

$$\begin{aligned} \epsilon^\alpha &\rightarrow C^\alpha \\ \beta^{\text{obs}} &\rightarrow b^{\text{obs}} \\ x &\rightarrow y \\ t &\rightarrow \Sigma \end{aligned}$$

$$\begin{aligned} \Delta_{FP}(\hat{g}, \hat{G}) &= \frac{1}{n_R} \int [dbdc] e^{\int d\Sigma dy_\alpha} \\ &\quad e^{- \int d\Sigma \bar{\Gamma}_g [b^{\text{obs}} (\bar{P}_C)_{\alpha\beta} + \xi \delta_{\alpha\beta}]} \\ &\quad e^{y_\alpha C^\alpha(\hat{G})} \end{aligned}$$

Integrate in ξ and y

$$\begin{aligned} \Delta_{FP}(\hat{g}, \hat{G}) &= \frac{1}{n_R} \int [dbdc] e^{- \int \frac{d\Sigma}{\pi} \left[\int d\Sigma \bar{\Gamma}_{\hat{g}} b^{\text{obs}} \delta_{\alpha\beta} \right]} \\ &\quad \times \frac{1}{\prod_{\alpha=1}^z} C^\alpha(\hat{G}) \end{aligned}$$

Torus amplitude

$$A_{\text{Torus}} = \frac{\int [dx][dg]}{V_{\text{diff. Weyl}}} \int_F d\alpha d\gamma_2 \Delta_{\text{FP}}(6, g) \\ \times \int_{\mathbb{Z}} dz \delta(g - \hat{g}(z)) \delta(6 - \hat{6}_1 z) \delta(6_2 - \hat{6}_2 z) e^{-S_x[g]_{V_i - V_0}}$$

This amplitude is meaningless unless an explicit $6_1, 6_2$ interpretation is explicated.

In the torus case, since the volume of the CUG is finite and equal to the volume of the torus itself, it is possible to introduce an interpretation of the form

$$1 = \frac{\int d^2 6}{V_{\text{Torus}}}$$

In other words, one fixes the CUG problem by just dividing away $V_{\text{CUG}} = V_{\text{Torus}}$?

No \rightarrow B- insertions in DFP?

In the general case, knowing $V_i = \int d^2 6 \delta_g V_i(6)$, we can identify the 6-dependence in DFP with the 6-dep. in $V_{K/2}$ vertex operators.

The CUG symmetry is fixed by fixing points on the manifold + including insertions in the path integral.

In the torus core, replacing the DFP

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$$A_{\text{torus}} = \frac{1}{N_R} \int \frac{dz_1 dz_2}{V_{\text{torus}}} \int [dx] [dbdc] \overline{\int d^2 \sqrt{\hat{g}} (b^{ab})_{z_2} g_{ab}} \times$$

$\frac{B_1}{B_2}$

$\times \int d^2 \sqrt{\hat{g}} (b^{ab})_{z_2} g_{ab} C'(G) C^2(G)$

$e^{-[\Sigma x + S_{\text{ghost}}]} \frac{V_i - V_u}{V_i + V_u}$

$N_R=2$

$= z_2$

Partition function

$$Z_{\text{torus}} = \frac{1}{2} \int_F \frac{dz_1 dz_2}{z_2} \langle B_1 B_2 C' C^2 \rangle_{\text{ghosts}}$$

$\times \langle 1 \rangle_{x\text{-fields}}$

\Rightarrow Relation with Coleman-Weinberg formula

\Rightarrow Role of the ghost partition function

\Rightarrow Self-regulation of UV divergences