

### 1.3 Feynman rules

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Generating functional:

$$Z[J] = \frac{1}{N} \int \mathcal{D}\phi e^{i\left[ S[\phi] + \int d^d x J(x) \phi(x) \right]} \quad (1.61)$$

with

$$\begin{aligned} & \langle 0 | T \hat{\phi}(x_1) \dots \hat{\phi}(x_n) | 0 \rangle / \langle 0 | 0 \rangle \\ &= (-i)^n \frac{\delta^n Z[J]}{\delta J(x_1) \dots \delta J(x_n)} \Big|_{J=0} \end{aligned} \quad (1.62)$$

where we have used

$$\frac{\delta J(x)}{\delta J(y)} := \delta^d(x-y) \quad (1.63)$$

For the free theory we have

$$Z_0[J] = e^{-\frac{1}{2} \int d^d x d^d y J(x) G(x,y) J(y)}$$

where  $(-\Delta - m^2)_x G(x,y) = i\delta^d(x-y)$  (1.64)

Examples: (i) 2-point fct.

$$\begin{aligned}
 \langle T \varphi(x) \varphi(y) \rangle &= - \frac{\delta^2 Z_0[J]}{\delta J(x) \delta J(y)} \Big|_{J=0} \\
 \langle 0 | T \hat{\varphi}(x) \hat{\varphi}(y) | 0 \rangle / \langle 0 | 0 \rangle & \\
 &= \frac{\delta^2}{\delta J(x) \delta J(y)} \int d^d x' d^d y' J(x') G(x', y') J(y') \\
 &= \underline{G(x, y)} \quad (1.65)
 \end{aligned}$$

(ii) 4-point fct.:

$$\begin{aligned}
 \langle T \varphi(x_1) \dots \varphi(x_4) \rangle &= \frac{\delta^4 Z_0[J]}{\delta J(x_1) \dots \delta J(x_4)} \Big|_{J=0} \\
 &= G(x_1, x_2) G(x_3, x_4) \\
 &\quad + \text{perms} \quad (1.66)
 \end{aligned}$$

Diagrammatically:

$$\langle T \varphi(x_1) \dots \varphi(x_4) \rangle = \begin{array}{c} 1 \text{ --- } 2 \\ 3 \text{ --- } 4 \end{array} + \begin{array}{c} 1 \\ | \\ 3 \end{array} \begin{array}{c} 2 \\ | \\ 4 \end{array} + \begin{array}{c} 1 \text{ --- } 2 \\ \diagdown \quad \diagup \\ 3 \quad 4 \end{array}$$

(iii) General 2n-point fct.:

$$\begin{aligned}
 \langle T \varphi(x_1) \dots \varphi(x_{2n}) \rangle &= (-i)^{2n} \frac{\delta^{2n} Z[J]}{\delta \varphi(x_1) \dots \delta \varphi(x_{2n})} \Big|_{J=0} \\
 &= \frac{(-i)^{2n}}{n!} \frac{\delta^{2n}}{\delta \varphi(x_1) \dots \delta \varphi(x_{2n})} \frac{(-1)^n}{2^n} \left[ \int d^d x d^d y J(x) G(x,y) J(y) \right]^n \\
 &= G(x_1, x_2) G(x_3, x_4) \dots G(x_{2n-1}, x_{2n}) \\
 &\quad + \text{perms.} \qquad (1.67)
 \end{aligned}$$

Schwinger functional:

$$\boxed{W[J] = \ln Z[J]} \qquad (1.68)$$

In the free case:

$$W_0[J] = \ln Z_0[J] = -\frac{1}{2} \int d^d x d^d y J(x) G(x,y) J(y) \qquad (1.69)$$

and hence

$$(-i)^2 \frac{\delta^2 W_0[J]}{\delta J(x_1) \delta J(x_2)} \Big|_{J=0} = G(x_1, x_2) \qquad (1.70)$$

In terms of  $Z_0$  this reads

$$\frac{\partial^2 W_0[J]}{\partial J(x_1) \partial J(x_2)} \Big|_{J=0} = \left( \frac{1}{Z_0} \frac{\delta^2 Z_0}{\delta J(x_1) \delta J(x_2)} - \frac{1}{Z_0} \frac{\delta Z_0}{\delta J(x_1)} \frac{1}{Z_0} \frac{\delta Z_0}{\delta J(x_2)} \right) \Big|_{J=0} \quad (1.71)$$

$$= \underbrace{\langle T \varphi(x_1) \varphi(x_2) \rangle - \langle \varphi(x_1) \rangle \langle \varphi(x_2) \rangle}_{\text{connected 2-point fct.}} \quad (1.71)$$

Here we have  $\langle \varphi(x_1) \rangle = \int dx G(x_1, x) J(x) \Big|_{J=0} = 0$  (1.72)

Interacting theory:  $S[\varphi] = S_0[\varphi] - \int d^d x V_{\text{int}}(\varphi)$

$$\begin{aligned} Z[J] &\approx \int \mathcal{D}\varphi e^{i\{S_0[\varphi] - \int d^d x V_{\text{int}}(\varphi) + \int d^d x J(x)\varphi(x)\}} \\ &= e^{-i\int d^d x V_{\text{int}}(-i\frac{\delta}{\delta J(x)})} \int \mathcal{D}\varphi e^{i\{S_0[\varphi] + \int d^d x J(x)\varphi(x)\}} \\ &\approx e^{-i\int d^d x V_{\text{int}}(-i\frac{\delta}{\delta J(x)})} Z_0[J] \quad (1.73) \end{aligned}$$

see also QM, eq. (1.44), p. 15.

Using eq. (1.64), p. 21. for  $Z_0$ , we get for eq. (1.73) :

$$Z[J] \approx e^{-i \int d^d x V_{\text{int}}(-i \frac{\delta}{\delta J(x)})} e^{-\frac{1}{2} \int_{x,y} J(x) G(x,y) J(y)} \quad (1.74)$$

with  $\int_x = \int d^d x$ ,  $\int_{x,y} = \int d^d x d^d y$ .

Assume for the moment, that  $V_{\text{int}}(\cdot)$  is small. Then we can expand  $Z$  in powers

of  $V$ :  $J \cdot G \cdot J = \int J(x) G(x,y) J(y)$

$$\begin{aligned} Z[J] &\approx \left[ 1 - i \int_x V_{\text{int}}\left(\frac{\delta}{\delta J}\right) - \frac{1}{2} \left( \int_x V_{\text{int}}\left(\frac{\delta}{\delta J}\right) \right)^2 + \dots \right] Z_0[J] \\ &= \left[ 1 - i \int_x V_{\text{int}}\left(\frac{\delta}{\delta J}\right) + \dots \right] \left( 1 - \frac{1}{2} \int_{x,y} J \cdot G \cdot J + \frac{1}{8} \left( \int_{x,y} J \cdot G \cdot J \right)^2 + \dots \right) \end{aligned} \quad (1.75)$$

In  $\varphi^4$ -theory we have  $V_{\text{int}}(\varphi) = \frac{\lambda}{4!} \varphi(x)^4$ ,

$$i \int_x V_{\text{int}}\left(\frac{\delta}{\delta J}\right) = \frac{i\lambda}{4!} \int_x \left(\frac{\delta}{\delta J(x)}\right)^4 \quad (1.76)$$

## Diagrammatics in $\varphi^4$ -theory:

(i) Vacuum 'physics': What is  $Z[0]$ ?

$$\begin{aligned}
 Z[0] &\simeq e^{-i \int_x V_{\text{int}} \left( \frac{\delta}{\delta J} \right)} e^{-\frac{1}{2} \int_{x,y} J \cdot G \cdot J} \Big|_{J=0} \\
 &\quad \textcircled{2} \\
 &= 1 - i \int_x V_{\text{int}} \left( \frac{\delta}{\delta J} \right) \frac{1}{2} \left( \frac{1}{2} \int_{x,y} J \cdot G \cdot J \right)^2 \\
 &\quad - \frac{1}{2} \left[ \int_x V \left( \frac{\delta}{\delta J} \right) \right]^2 \frac{1}{4!} \left( -\frac{1}{2} \int_{x,y} J \cdot G \cdot J \right)^4 \\
 &\quad \textcircled{\beta} \\
 &\quad + \dots \quad (1.77)
 \end{aligned}$$

(a) Each  $J$ -derivative can hit each current  $J$ .

(b) Due to the symmetry of  $G$ :  $G(x,y) = G(y,x)$

we have  $\frac{\delta}{\delta J(x_1)} \frac{\delta}{\delta J(x_2)} \frac{1}{2} \int_{x,y} J \cdot G \cdot J = G(x_1, x_2)$ .

$\Rightarrow$  (c) We simply have to work-out all permutations

$\Rightarrow$  best done diagrammatically

(or computer)

Diagrams:

$$-i\frac{\lambda}{4!} \int_x \left( \frac{\delta}{\delta J(x)} \right)^4 \sim \text{X}_x \quad \text{vertex: } -i\lambda$$

(b)  $\rightarrow -\frac{1}{2} \int_{x,y} j(x) G(x,y) j(y) \sim \overline{x-y}$  propagator

'Computation' of  $Z[0]$ : eq. (1.77)

$\alpha$ :  $\frac{1}{8} \frac{1}{4!} \left( \text{X}_{43}^{12} \right) \cdot 4!$  ← from taking derivatives  
 permutations of attaching vertex legs with props.

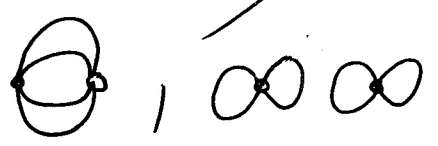
$$= \frac{1}{8} \text{diagram} = -\frac{i\lambda}{8} \int d^d x G(x,x) G(x,x)$$

divergent, see QFT I

$\beta$ :  $\frac{1}{4!} \frac{1}{2^4} \frac{1}{2} \left( \frac{1}{4!} \right)^2 = \text{X} \text{X}$

$$= \frac{1}{4!} \frac{1}{2^4} \frac{1}{2} \left( \frac{1}{4!} \right)^2 \text{combs.} \text{diagram} + \dots$$

↑  
(exercise)



Remark: What about  $Z_0[0]$ ?

We use

$$\begin{aligned} \int \mathcal{D}\varphi e^{iS_0[\varphi]} &\simeq \det^{-1/2}(-\Delta - m^2) \\ &\simeq \det^{1/2} G \end{aligned} \quad (1.78)$$

Furthermore we have

$$\begin{aligned} \det \mathcal{M} &= \prod_n \lambda_n = \prod_n e^{\ln \lambda_n} = e^{\sum_n \ln \lambda_n} \\ &= e^{\text{Tr} \ln \mathcal{M}} \end{aligned} \quad (1.79)$$

For  $Z_0[0]$  this implies

$$Z_0[0] \simeq \det^{1/2} G = e^{\frac{1}{2} \text{Tr} \ln G} \quad (1.80)$$

$$\text{and } \text{Tr} \ln G = \int d^d x \ln G(x, x)$$

or diagrammatically (with  $\partial_{m^2} G = iG^2$ )

$$\frac{1}{Z_0[0]} \partial_{m^2} Z_0[0] \simeq \frac{i}{2} \bigcirc \quad (1.81)$$



Correlation fcts.:

$$\begin{aligned}
 \langle T \varphi(x_1) \dots \varphi(x_n) \rangle &= \frac{(-i)^n}{Z[J]} \frac{\delta^n Z[J]}{\delta \varphi(x_1) \dots \delta \varphi(x_n)} \Big|_{J=0} \\
 &= \frac{(-i)^n}{1 + \text{vac. diag.}} \frac{\delta^n}{\delta \varphi(x_1) \dots \delta \varphi(x_n)} e^{-i \int_x V_{\text{int}}(\frac{\delta}{\delta J})} e^{-\frac{i}{2} \int_{x,y} J \cdot G \cdot J} \\
 &= (-i)^n \left[ \frac{\delta^n}{\delta \varphi(x_1) \dots \delta \varphi(x_n)} e^{-i \int_x V_{\text{int}}(\frac{\delta}{\delta J})} e^{-\frac{i}{2} \int_{x,y} J \cdot G \cdot J} \right]_{\text{no vac. contrib.}}
 \end{aligned}$$

(1.82)

⇒ Feynman rules:

Propagator:  $x \text{---} y = G(x, y)$

Vertex:  $\text{---} \times \text{---} = -i \lambda \int d^4 x$

(a) Write down all diagrams in a given order  $N$  of  $\lambda$  of  $2n$ -point correlation fct.

(b) Combinatorial factors of diagrams

$$\sum_N \left( \frac{1}{4!} \right)^N \frac{1}{N!} \left[ \int_x \frac{\delta}{\delta J} \right]^N \frac{1}{(2N+n)!} \left[ \frac{1}{2} \int_{x,y} J \cdot G \cdot J \right]^{2N+n}$$

$\uparrow$   $\uparrow$   $\uparrow$   $\uparrow$   
 $N$  loops

Example: 2-point fct.

$$\langle T \varphi(x_1) \varphi(x_2) \rangle = \frac{1}{x_1 - x_2} + \frac{1}{2} \text{loop} + \dots$$

$\frac{1}{3!} \frac{1}{8} \frac{1}{4!} \cdot 4! \frac{4!}{4 \cdot 6} \frac{1}{4!} \left( \frac{\partial}{\partial J} \right)^4 \frac{\partial}{\partial J(x_1)} \frac{\partial}{\partial J(x_2)}$

The above results extend straight forwardly to general scalar theories.

Example:  $S[\varphi, \phi] = \frac{1}{2} \int_x \{ \varphi(-\Delta - m_\varphi^2) \varphi + \phi(-\Delta - m_\phi^2) \phi - \frac{1}{2} \int_x \phi \varphi^2 \quad (1.83)$

Generating functional:

$$Z[J_\varphi, J_\phi] = \int \mathcal{D}\varphi \mathcal{D}\phi e^{i \int S[\varphi, \phi] + \int_x (J_\varphi \varphi + J_\phi \phi)}$$

$$\simeq e^{-\frac{i}{2} \int_x \frac{\delta}{\delta J_\varphi} \frac{\delta^2}{\delta J_\varphi^2}} Z_0[J_\varphi, J_\phi]$$

with

$$Z_0[J_\varphi, J_\phi] \simeq e^{-\frac{1}{2} \int_{x,y} (J_\varphi \cdot G_\varphi J_\varphi + J_\phi G_\phi J_\phi)} \quad (1.84)$$

$$(-\Delta_x - m_\varphi^2 / \phi) G_{\varphi/\phi}(x, y) = i \delta(x - y) \quad (1.85)$$

# Wick rotation & statistical interpretation

The functional integrals are defined with measures  $d\varphi e^{iS[\varphi]}$ . For practical purposes (perturbative evaluation, numerics) it is convenient, and necessary, to perform a Wick rotation (see also QFT I):

$$\boxed{x_{0\mu} \rightarrow -i x_{0E}} : \boxed{e^{-i\Delta t H} \rightarrow e^{-\Delta t H}}$$

$$\Rightarrow i \int d^d x_{\mu} \rightarrow + \int d^d x_E$$

$$- \partial_{\nu} \partial^{\nu} \rightarrow + \partial_{\nu} \partial_{\nu}$$
(1.86)

$\varphi$  scalar:  $\varphi \rightarrow \varphi$

$$\Rightarrow i \int d^d x \left\{ \frac{1}{2} \varphi (-\partial_{\nu} \partial^{\nu}) \varphi - V(\varphi) \right\}$$

S[\varphi] Minkowski

(1.87)

$$\rightarrow - \int d^d x \left\{ \frac{1}{2} \varphi (-\partial_{\nu} \partial_{\nu}) \varphi + V(\varphi) \right\}$$

S[\varphi] Euclidean

$$\boxed{S[\varphi] \geq 0}$$

Generating Functional:

$$Z_{\text{Euclidean}}[J] = \int \mathcal{D}\varphi e^{-S[\varphi] + \int d^d x J(x) \varphi(x)} \quad (1.88)$$

with  $\langle T \varphi(x_1) \dots \varphi(x_n) \rangle_{\text{Eucl.}} = \frac{\delta^n Z}{\delta J(x_1) \dots \delta J(x_n)}$  (1.89)

Free theory:  $S_0[\varphi] = \frac{1}{2} \int d^d x \varphi (-\overset{\Delta_E = \partial_\mu \partial_\mu}{\Delta} + m^2) \varphi$

$$Z_0[J] = \int \mathcal{D}\varphi e^{-S_0[\varphi] + \int d^d x J(x) \varphi(x)}$$

$$= \det^{-1/2} \underbrace{(-\Delta + m^2)}_{\geq 0} e^{\frac{1}{2} \int d^d x J(x) G(x, y) J(y)} \quad (1.90)$$

with  $(-\Delta + m^2) G(x, y) = \delta^d(x - y)$  (1.91)

Wick rotation on Propagators

$$G_M(p) = \frac{i}{p_M^2 - m^2 + i\epsilon} \longrightarrow G_E(p) = \frac{1}{p^2 + m^2}$$

Vertex

$$-i\lambda \longrightarrow -\lambda$$

The Euclidean functional integral is a statistical integral with statistical measure  $d\phi e^{-S[\phi]}$  (not normalised).

The Schwinger functional is nothing but the free energy  $F$ .

Euclidean correlation fcts. can be Wick-rotated back to Minkowski space (or real time), where they provide the real-time correlation fcts.:

$$\begin{aligned} & \langle T \phi(x_1) \dots \phi(x_n) \rangle_{\text{Eud.}} (x_{i0E} \rightarrow i x_{i0M}) \\ & = \langle T \phi(x_1) \dots \phi(x_n) \rangle_{\text{Mink.}} \end{aligned} \quad (1.92)$$