

# Automatic Differentiation for Reconstructing Spectral Functions with Neural Networks

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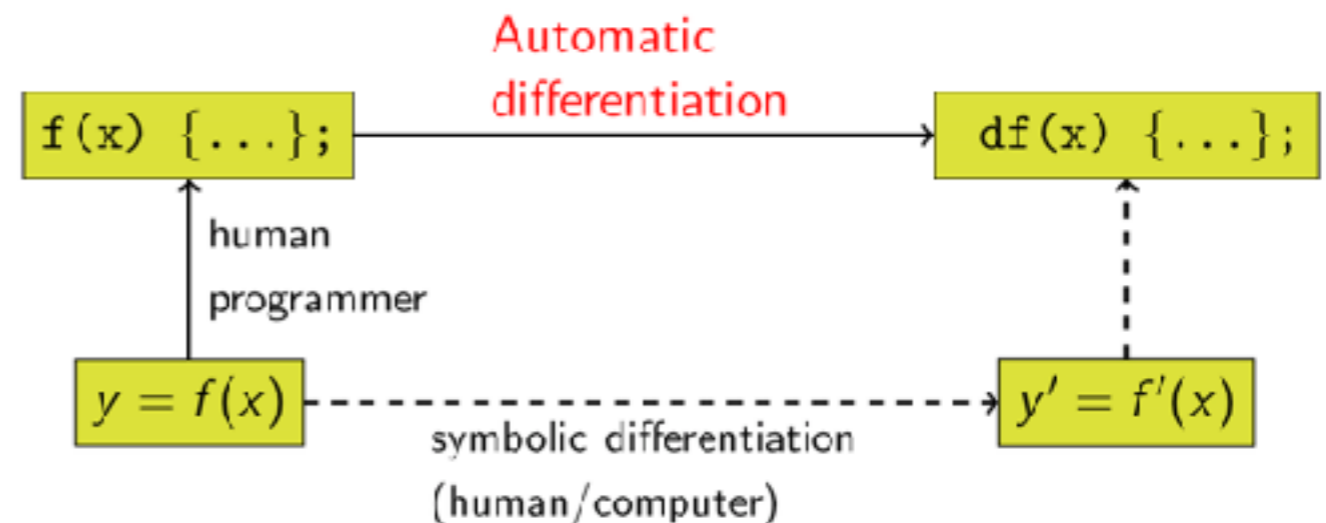
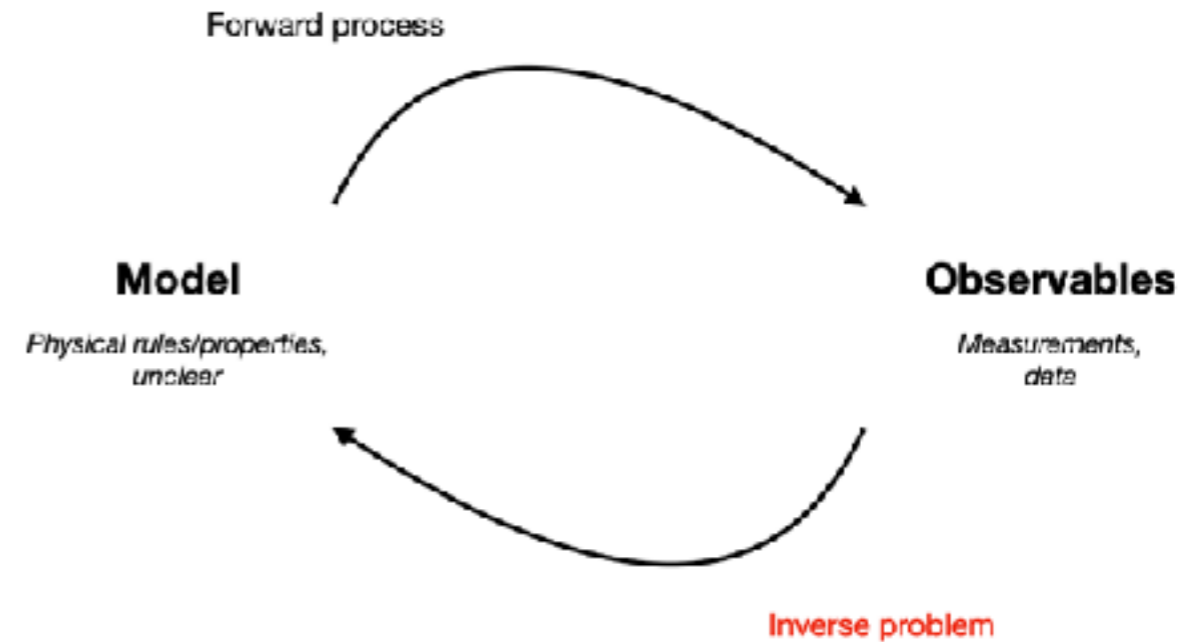
physics paper is preparing

09 Nov. 2021, "**Cold Quantum Coffee**" seminar, ITP of Heidelberg University

# Main Content

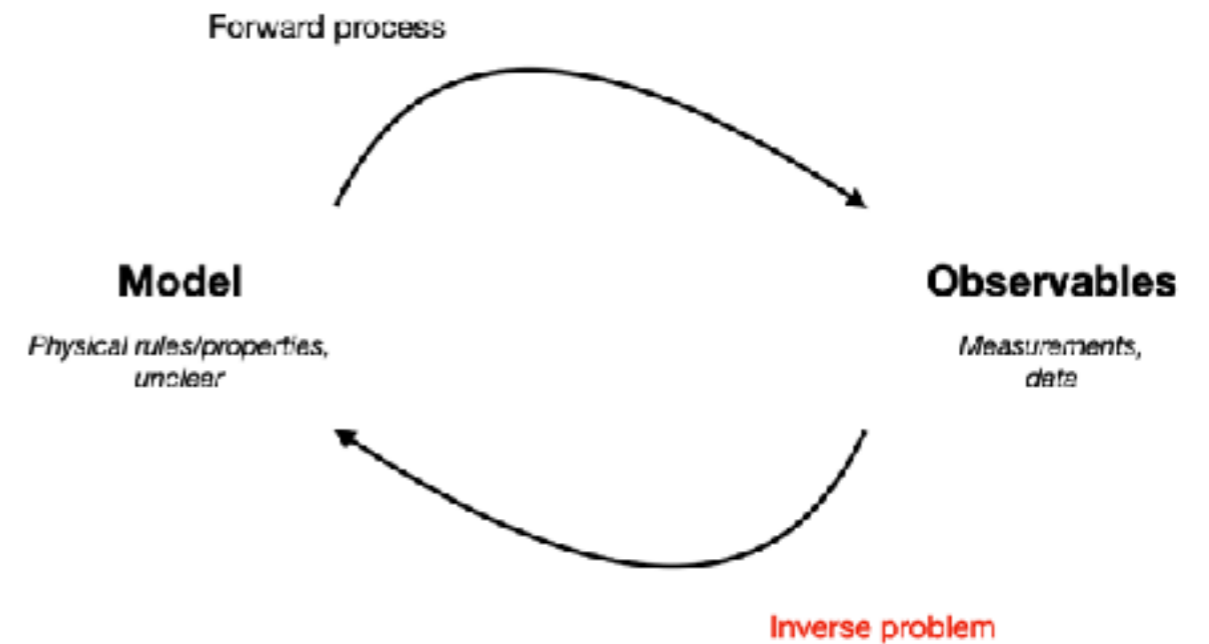
## AD for Inverse Problem

- Inverse Problem
  - Ill-posed problem
  - Reconstruct spectral functions
- **AD** for reconstruction
  - AD framework
    - Automatic Differentiation
    - Neural Network representations
  - Preliminary results
- Summary



**Inverse problem**

# Inverse Problem



- **Mathematics**
- **IP in Physics**
  - QCD physics
  - Condensed matter physics
  - Optics
- **IP in Science and Technology**
  - Signal processing
  - Epidemiology
  - Material design
  - ...

$$O = M(p) + N$$

- $O$ : Observations/Outcomes
- $M$ : Model/Function
- $p$ : Parameters/Incomes
- $N$ : Noise in real-world

Tarantola, A. (2005). *Inverse problem theory and methods for model parameter estimation*.

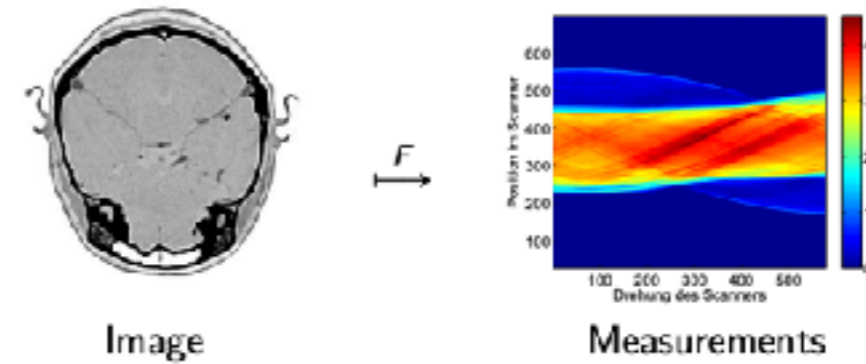
# Inverse Problem

## Examples

- **Ill-posed problem**
  - A small error in the initial measurements can result in large deviations of reconstructions
  - **Noise** and **discontinuities** of observed data
- **Medical physics**
  - From x-ray intensity to tissue image
- **Image processing**
  - Deblurring
- **Numerical differentiation**

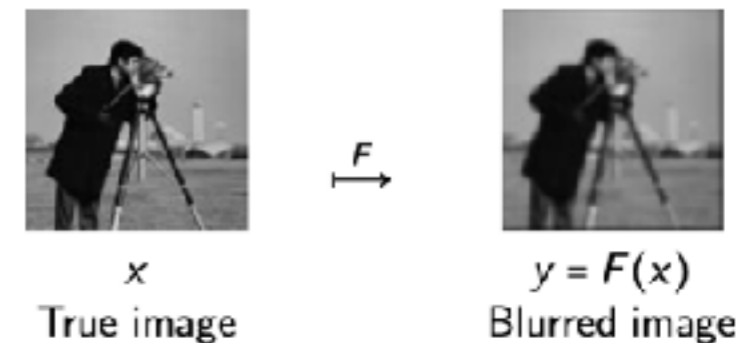
Hadamard (1865–1963): A problem is called well-posed, if a solution exists, the solution is unique, and the solution depends continuously on the given data.

## Computerized tomography (CT)



- Direct problem:** Simulate/predict the measurements  
(from knowledge of the interior density distribution)  
*Given  $x$  calculate  $F(x) = y!$*
- Inverse problem:** Reconstruct/image the interior distribution  
(from taking x-ray measurements)  
*Given  $y$  solve  $F(x) = y!$*

## Image deblurring



- Direct problem:** Simulate/predict the blurred image  
(from knowledge of the true image)  
*Given  $x$  calculate  $F(x) = y!$*
- Inverse problem:** Reconstruct/image the true image  
(from the blurred image)  
*Given  $y$  solve  $F(x) = y!$*

B. Harrach (2015). *Introduction to Inverse Problems*

Tarantola, A. (2005). *Inverse problem theory and methods for model parameter estimation.*

# Inverse Problem

## Examples

- **Ill-posed problem**

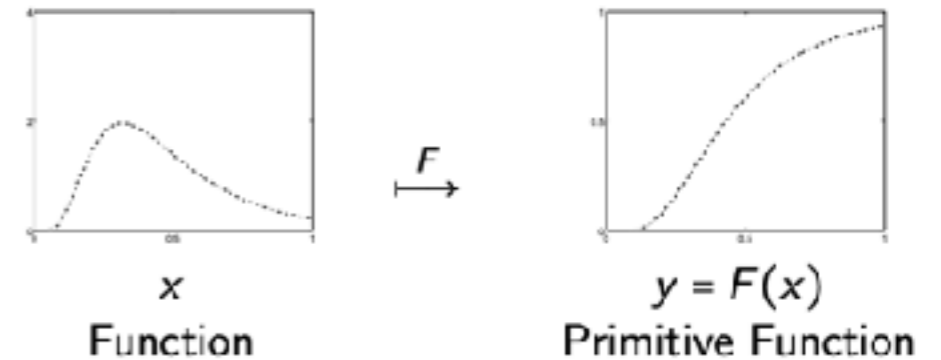
- A small error in the initial measurements can result in large deviations in reconstructions
- **Noise** and **discontinuities** of observed data

- **Numerical differentiation**

- $F$  is an integral operation
- step length  $h = 10^{-3}$
- rebuilt error  $\delta \rightarrow 0, y^\delta \rightarrow \hat{y}$
- Optics, Condensed matter, QCD Physics,...

Hadamard (1865–1963): A problem is called well-posed, if a solution exists, the solution is unique, and the solution depends continuously on the given data.

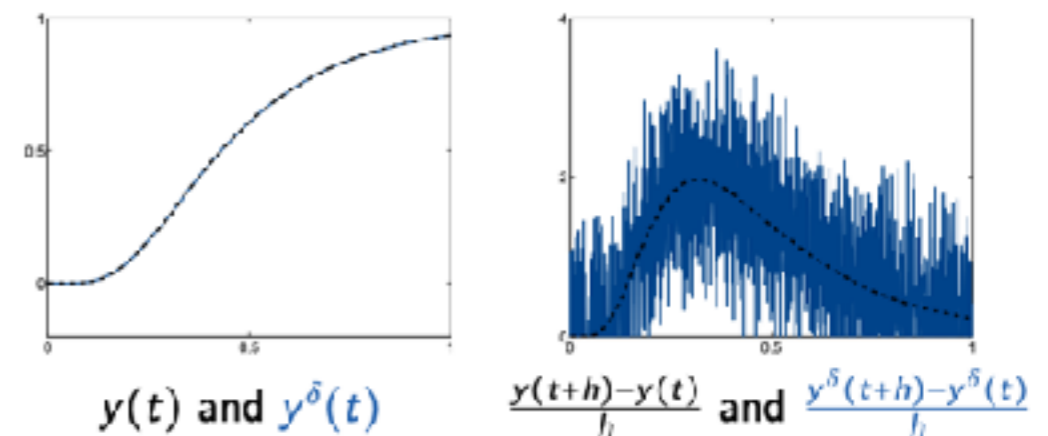
## Numerical differentiation



**Direct problem:** Calculate the primitive  
Given  $x$  calculate  $F(x) = y!$

**Inverse problem:** Calculate the derivative  
Given  $y$  solve  $F(x) = y!$

### Numerical differentiation example ( $h = 10^{-3}$ )

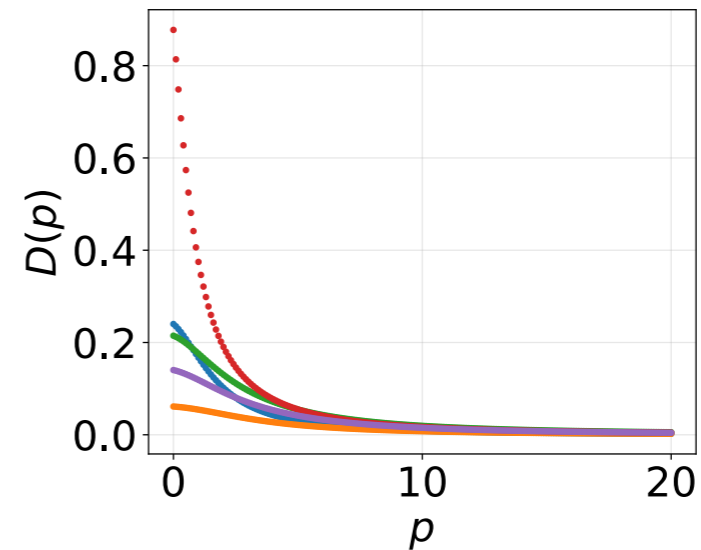


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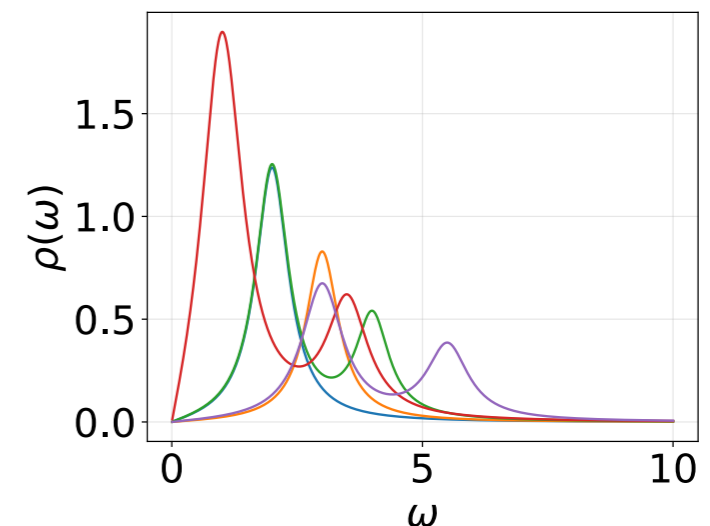
# Inverse Problem

## Rebuild spectral functions

- **Real-time properties of strongly correlated quantum systems**
  - Time has to be analytically continued into the complex plane
  - Reconstruct the **spectral function** from **noisy Euclidean propagator** data (e.g., Lattice QCD) to extract their physical structures
- **Methods**
  - **Classical methods**
    - Truncated Singular Value Decomposition (TSVD)
    - Tikhonov regularization, ...  
H. W. Engl and C. W. Groetsch, editors, *Inverse and Ill-Posed Problems* (Academic Press, Boston, 1987).
  - **Bayesian methods: Maximum Entropy Method (MEM)**  
M. Jarrell and J. E. Gubernatis, *Bayesian Inference and the Analytic Continuation of Imaginary-Time Quantum Monte Carlo Data*, *Physics Reports* **269**, 133 (1996).  
M. Asakawa, Y. Nakahara, and T. Hatsuda, *Maximum Entropy Analysis of the Spectral Functions in Lattice QCD*, *Progress in Particle and Nuclear Physics* **46**, 459 (2001).
  - Supervised learning inverse mapping
  - Gaussian process, Radial Basis Functions(RBF), sVAE



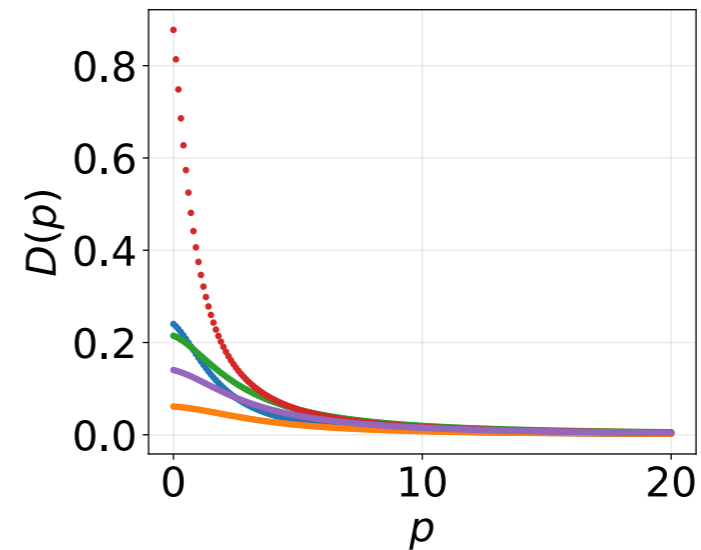
$$D(p) \equiv \int_0^{\infty} K(p, \omega) \rho(\omega) d\omega$$



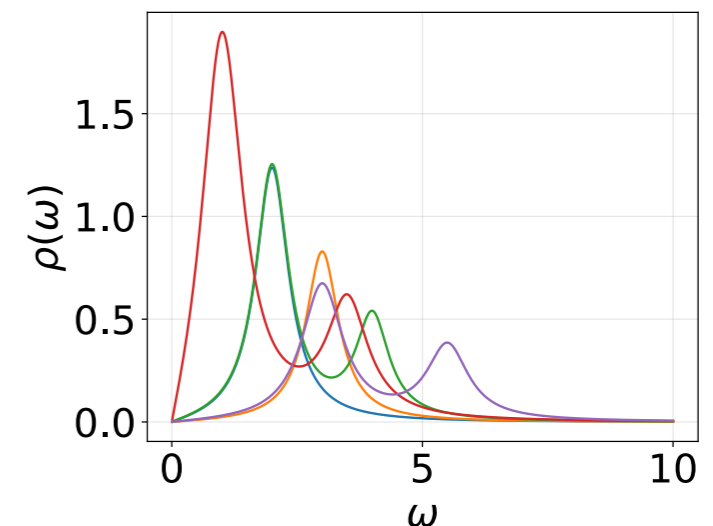
# Inverse Problem

## Rebuild spectral functions

- **Real-time properties of strongly correlated quantum systems**
  - Time has to be analytically continued into the complex plane
  - Reconstruct the **spectral function** from **noisy Euclidean propagator** data (e.g., Lattice QCD) to extract their physical structures
- **Methods**
  - Classical methods
  - Bayesian methods: Maximum Entropy Method (MEM)
  - **Supervised Learning** inverse mapping
    - L. Kades, J. M. Pawłowski, A. Rothkopf, M. Scherzer, J. M. Urban, S. J. Wetzel, N. Wink, and F. P. G. Ziegler, *Spectral Reconstruction with Deep Neural Networks*, Phys. Rev. D **102**, 096001 (2020).
    - R. Fournier, L. Wang, O. V. Yazyev, and Q. Wu, *Artificial Neural Network Approach to the Analytic Continuation Problem*, Phys. Rev. Lett. **124**, 056401 (2020).
    - H. Yoon, J.-H. Sim, and M. J. Han, *Analytic Continuation via Domain Knowledge Free Machine Learning*, Phys. Rev. B **98**, 245101 (2018).
  - **Gaussian process, Radial Basis Functions(RBF), sVAE(Variational AutoEncoder)**
    - ArXiv:2107.13464, ArXiv:2106.08168, ArXiv:2110.13521



$$D(p) \equiv \int_0^{\infty} K(p, \omega) \rho(\omega) d\omega$$





# Inverse Problem

## Mock data

- **Real-time properties of strongly correlated quantum systems**

- Reconstruct the **spectral function** from **noisy Euclidean propagator** data (e.g., Lattice QCD) to extract their physical structures

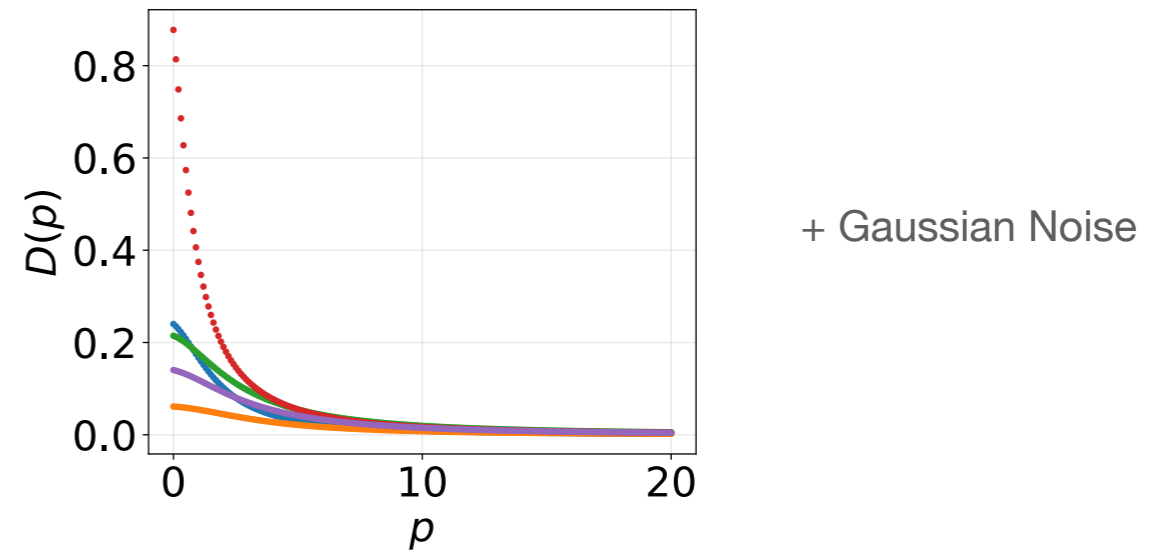
- Mock Data

- *Kallen–Lehmann(KL)* representation

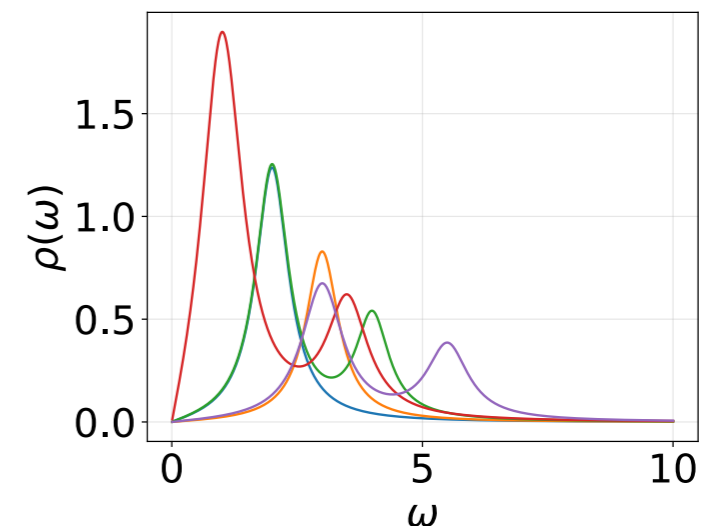
$$D(p) = \int_0^\infty \frac{\omega \rho(\omega)}{\omega^2 + p^2} \frac{d\omega}{\pi}$$

- Breit-Wigner peaks  $\rho^{(BW)}(\omega) = \frac{4A\Gamma\omega}{(M^2 + \Gamma^2 - \omega^2)^2 + 4\Gamma^2\omega^2}$

A parametrization obtained directly from one-loop perturbative quantum field theory:  
*A*: amplitude,  $\Gamma$ : width, *M*: mass



$$D(p) \equiv \int_0^\infty K(p, \omega) \rho(\omega) d\omega$$



# **Automatic Differentiation for Reconstruction**

# Framework

## Automatic differentiation

- **Automatic differentiation (AD)**

- It refers to a general way of taking a program which **computes a value**, and **automatically constructing a procedure for computing derivatives of that value.**

- **Example**

How we compute the derivatives of logistic least squares regression in a net

$w$  weights,  $b$  bias,  $\sigma(z)$  activation function  
 $x$  input,  $y$  output,  $t$  target,  $\mathcal{L}$  loss function



Chain rule:  $h'(x) = f'(g(x))g'(x).$

Computing the loss:

$$z = wx + b$$

$$y = \sigma(z)$$

$$\mathcal{L} = \frac{1}{2}(y - t)^2$$

Computing the derivatives:

$$\bar{\mathcal{L}} = 1$$

$$\bar{y} = y - t$$

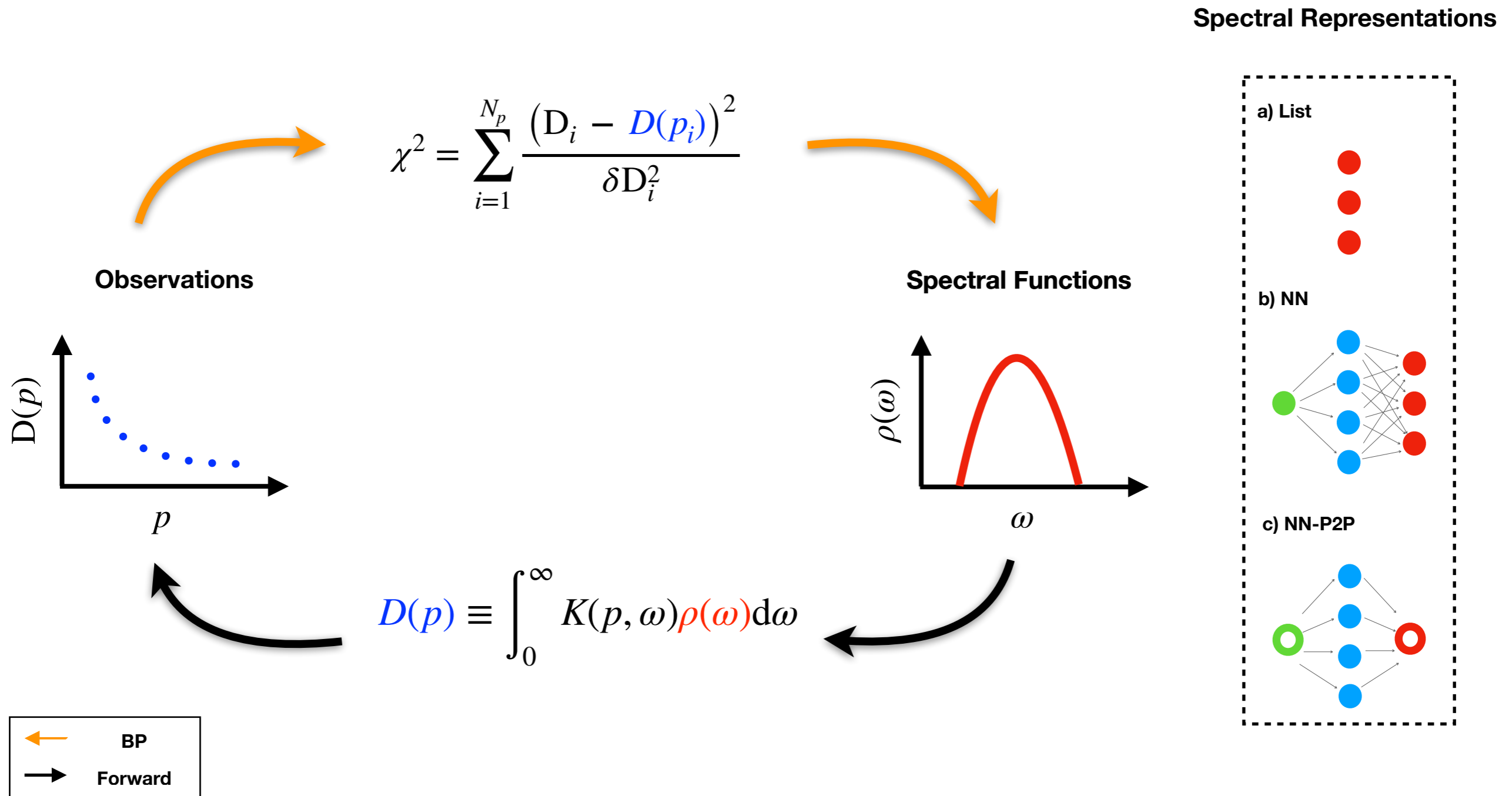
$$\bar{z} = \bar{y}\sigma'(z)$$

$$\bar{w} = \bar{z}x$$

$$\bar{b} = \bar{z}$$

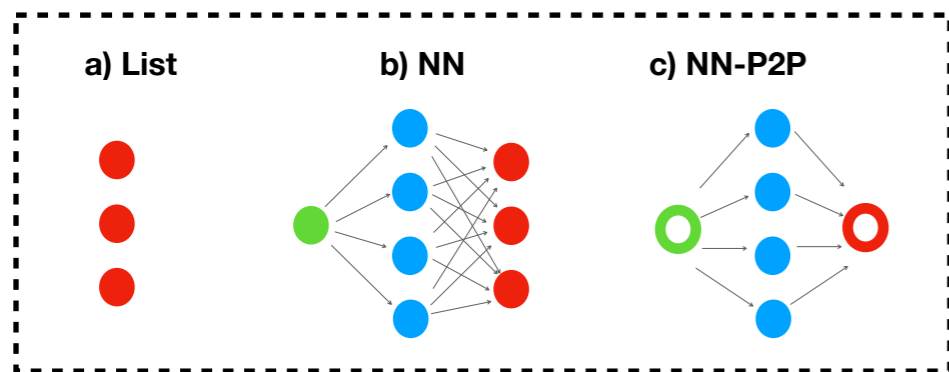
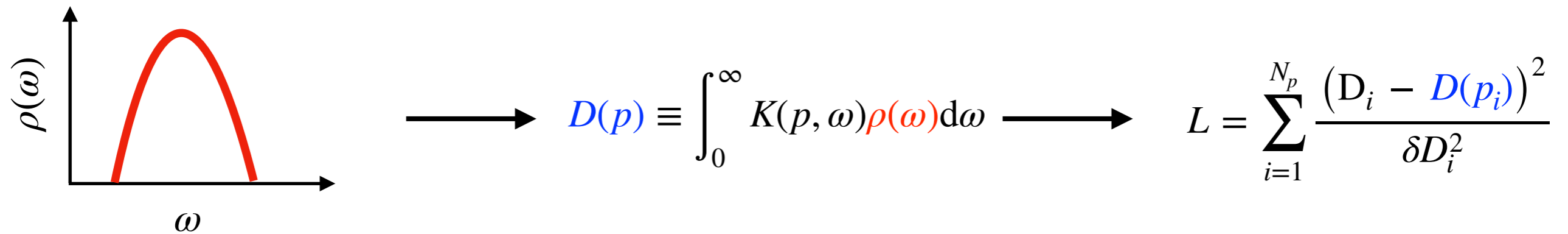
# Framework

## Automatic differentiation

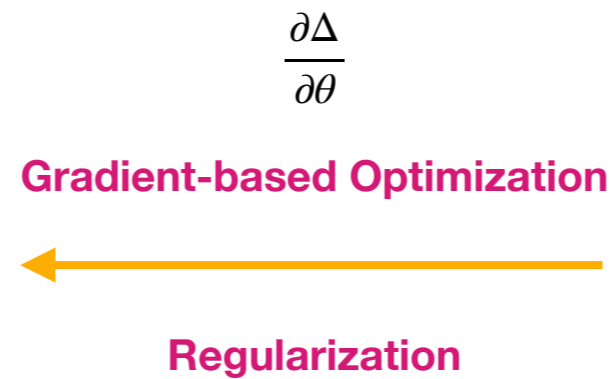


# Framework

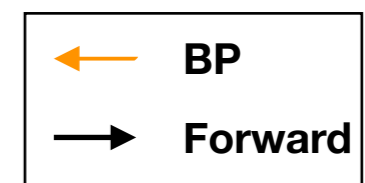
## Automatic differentiation



- a) List :  $(\rho_1, \rho_2, \dots, \rho_{N_\omega})$
- b) NN :  $(\rho_1, \rho_2, \dots, \rho_{N_\omega})$
- c) NN-P2P :  $\rho_i(\omega_i)$

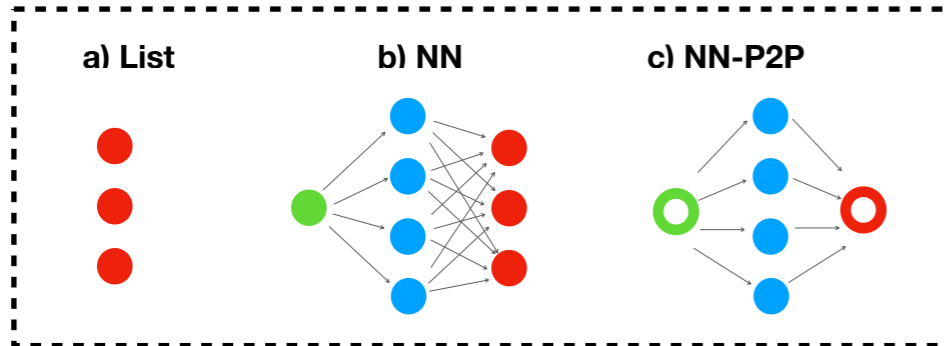


$$\Delta = \frac{\partial L}{\partial D(p)} K(p, \omega)$$



# Framework

## Back-propagation



Gradient-based Optimization



Regularization

$$\Delta = \frac{\partial L}{\partial D(p)} K(p, \omega)$$

a) **List** :  $(\rho_1, \rho_2, \dots, \rho_{N_\omega})$

Differentiable variables :  $\rho_i$

Adam, L2 ( $\lambda = 10^{-3} \rightarrow 0$ ), Smoothness ( $\lambda_s = 10^{-4} \rightarrow 0$ )

b) **NN** :  $(\rho_1, \rho_2, \dots, \rho_{N_\omega})$

Differentiable variables : Network weights  $\{\theta\}$

Adam, L2 ( $\lambda = 10^{-3} \rightarrow 0$ ), Smoothness ( $\lambda_s = 10^{-4} \rightarrow 0$ )

c) **NN-P2P** :  $\rho_i(\omega_i)$

Differentiable variables : Network weights  $\{\theta\}$

Adam, L2 ( $\lambda = 10^{-6} \rightarrow 0$ )

Gradient-based Optimization

$$\text{Adam} : \theta_{t+1} = \theta_t - \frac{\eta}{\sqrt{\hat{v}_t} + \epsilon} \hat{m}_t$$

Regularization

$$\text{L2} : \lambda \|\theta\|_2^2$$

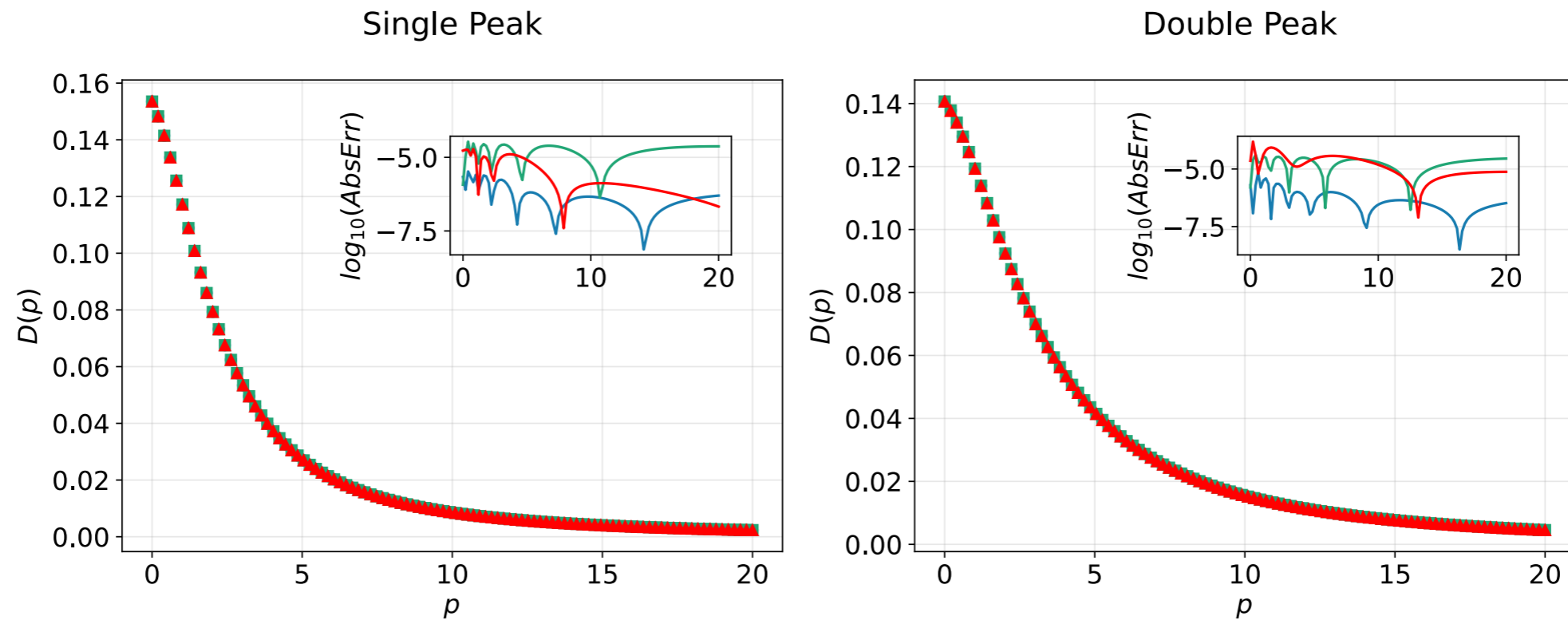
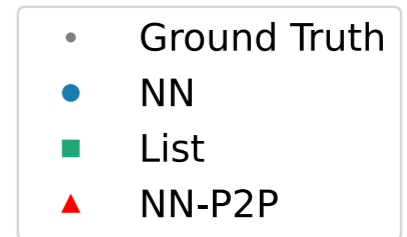
$$\text{Smoothness} : \lambda_s \sum_i^{N_\omega} (\rho_i - \rho_{i-1})^2$$

Physical Prior

Positive-defined condition: Softplus  $\log(1 + e^x)$

# Preliminary results

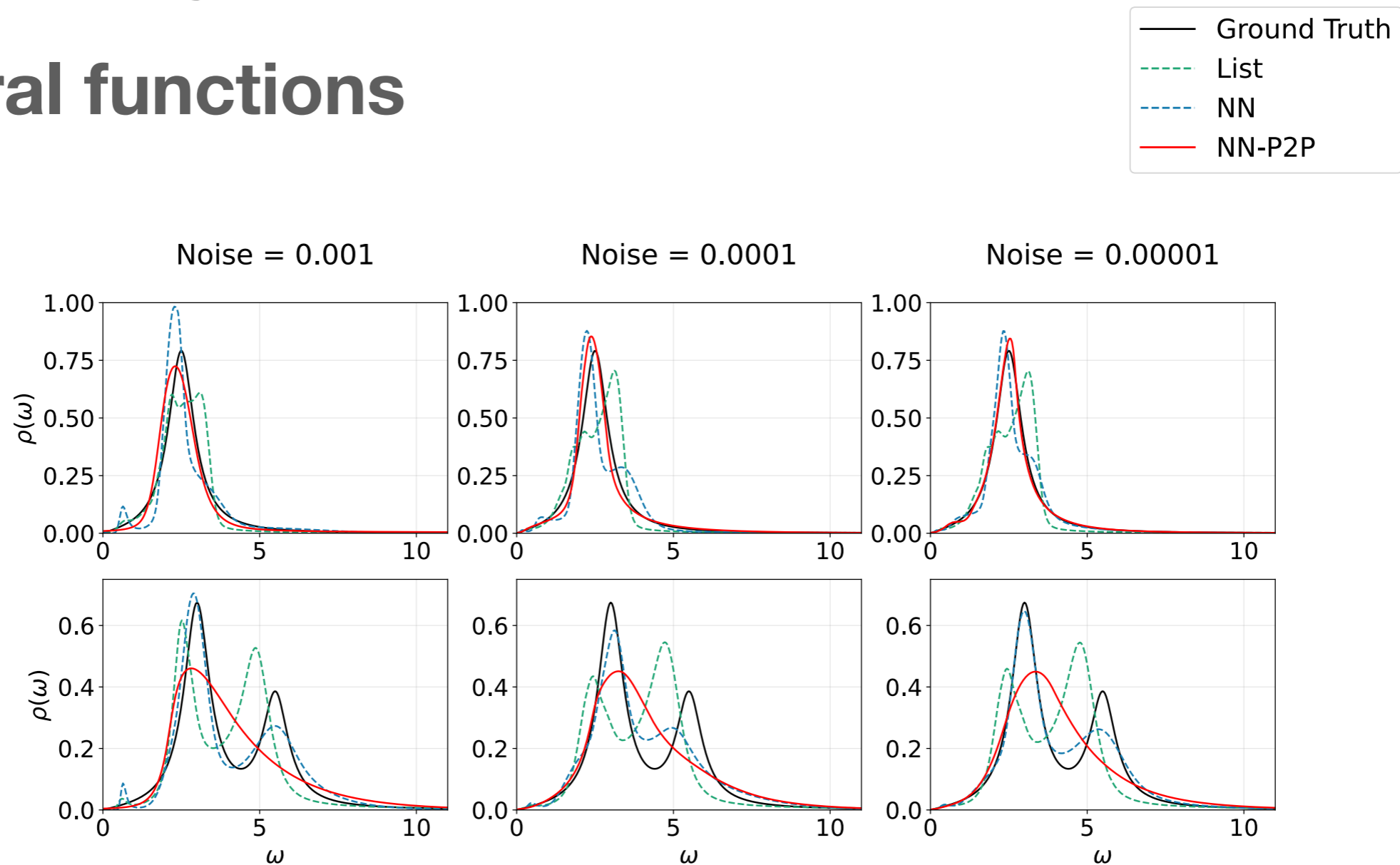
## Reconstruction correlators



- Two samples : spectral functions with single or double Breit-Wigner peaks
- **Reconstruction absolute error**  $|D_i - D(p_i)| < 10^{-5}$  as the same magnitude of noise

# Preliminary results

## Spectral functions



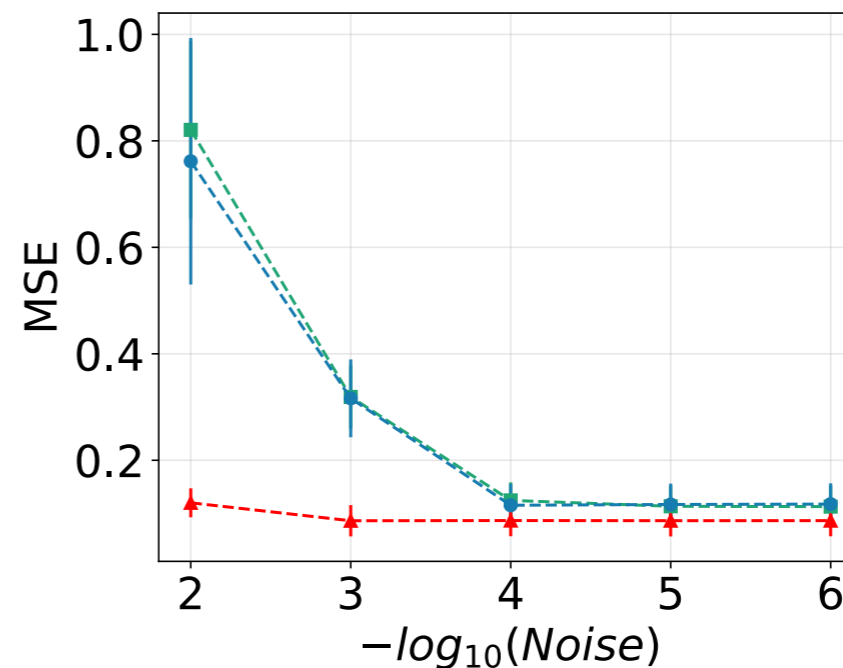
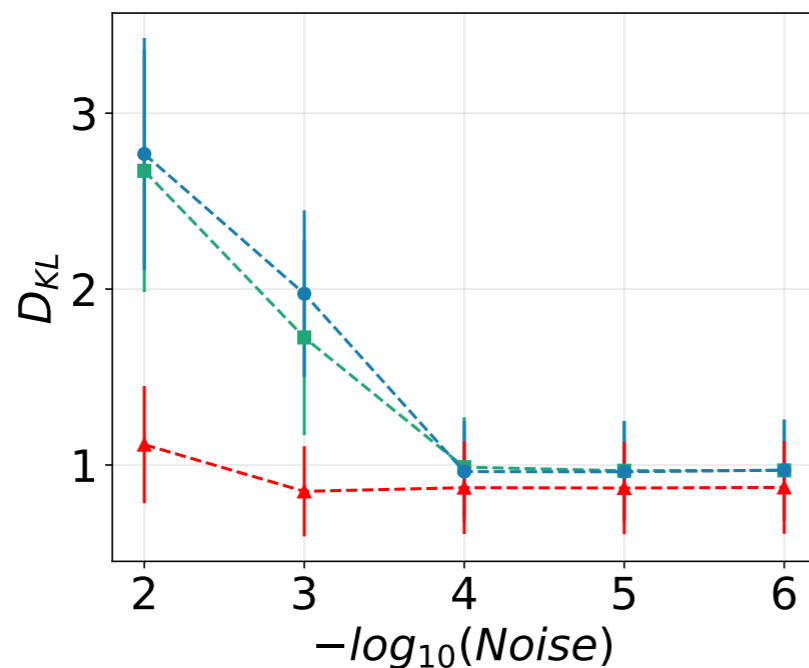
- **Reconstruction performance** will be better with noise decreasing
- **NN-P2P** gets the best consistency in single peak case
- NN and List can represent a more diverse spectrum in double peak case



# Preliminary results

## Quantified Evaluation

$$D_{KL}(p||q) = \int d\mathbf{x} p(\mathbf{x}) \log \frac{p(\mathbf{x})}{q(\mathbf{x})}$$



- 100 spectra with mixed single and double peaks
- K-L divergence and MSE decreasing with noise decreasing
- **NN-P2P** is better than others, because its intrinsic continuity of one-to-one mapping

# Summary

# Summary and Outlooks

- **Take-home messages**

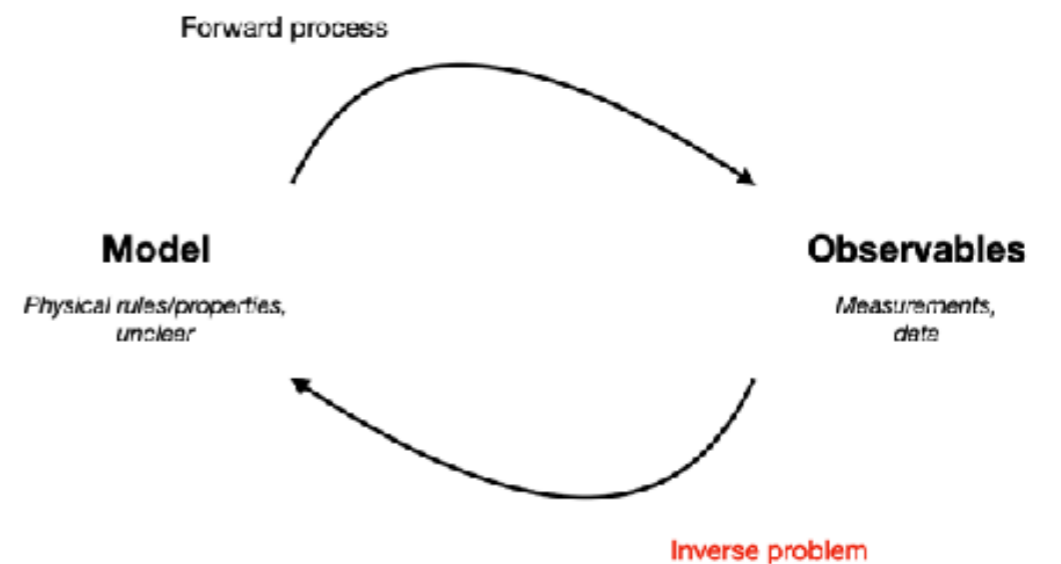
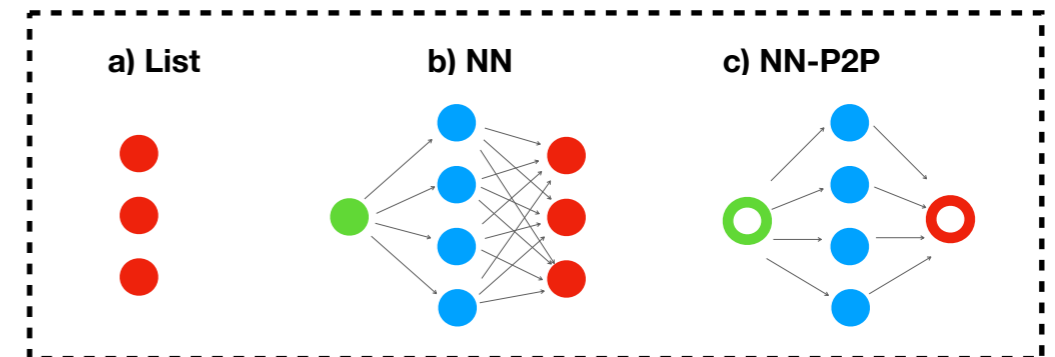
- **AD** can solve **inverse problem** using **error information** unsupervisedly
- **Neural network representations** can help us to embed **physical regularization** into **reconstructing**

- **Future works**

- Optimization algorithm
- Maximum Entropy Method (MEM)

- **Related works**

- Neutron Star, *in preparing*
- Bottonium potential, *arXiv:2105.07862*



# Summary and Outlooks

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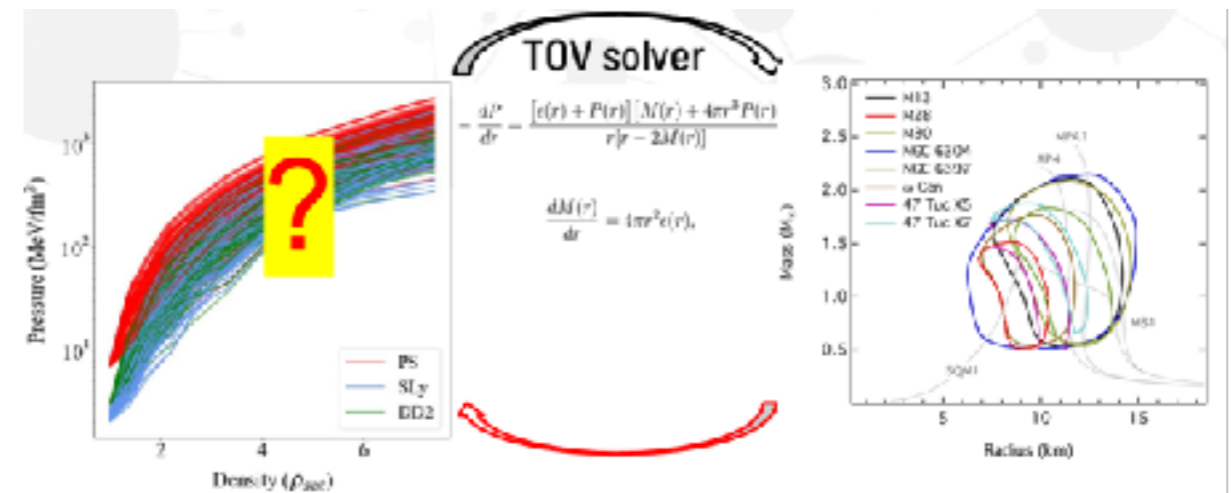
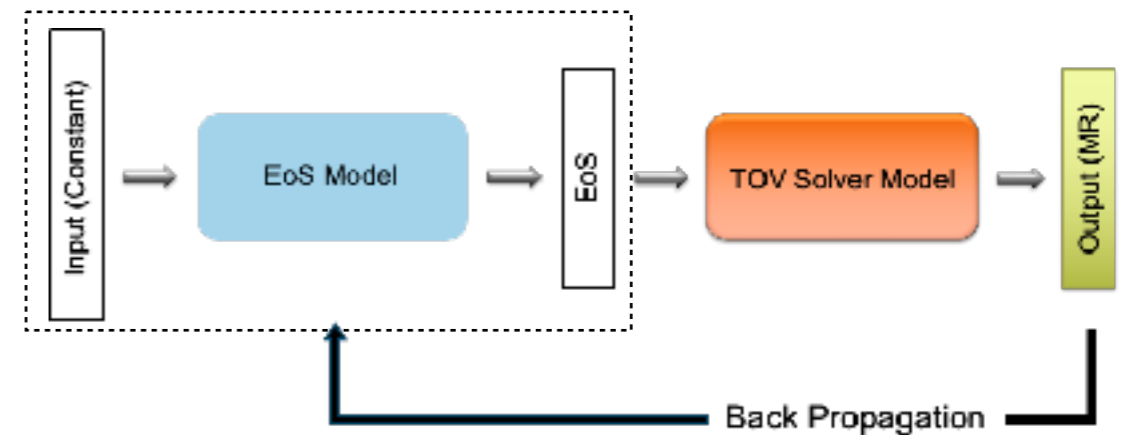
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## Neural Networks



# Summary and Outlooks

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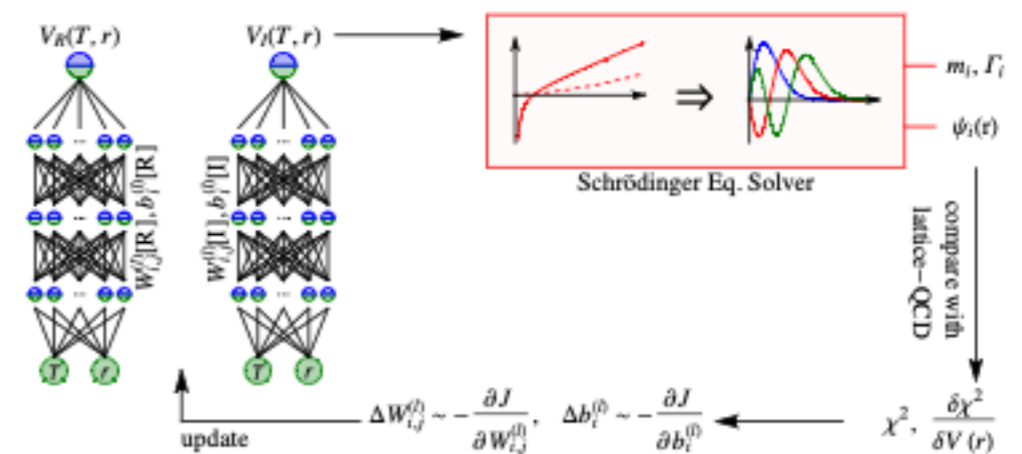
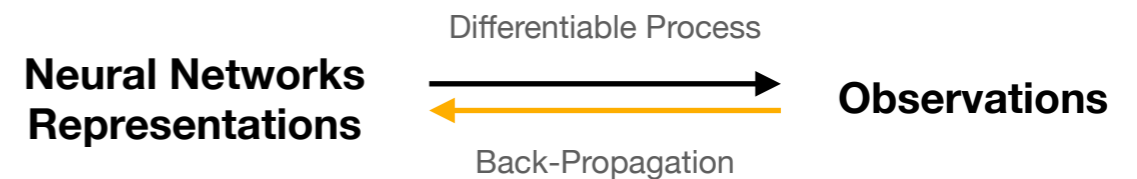
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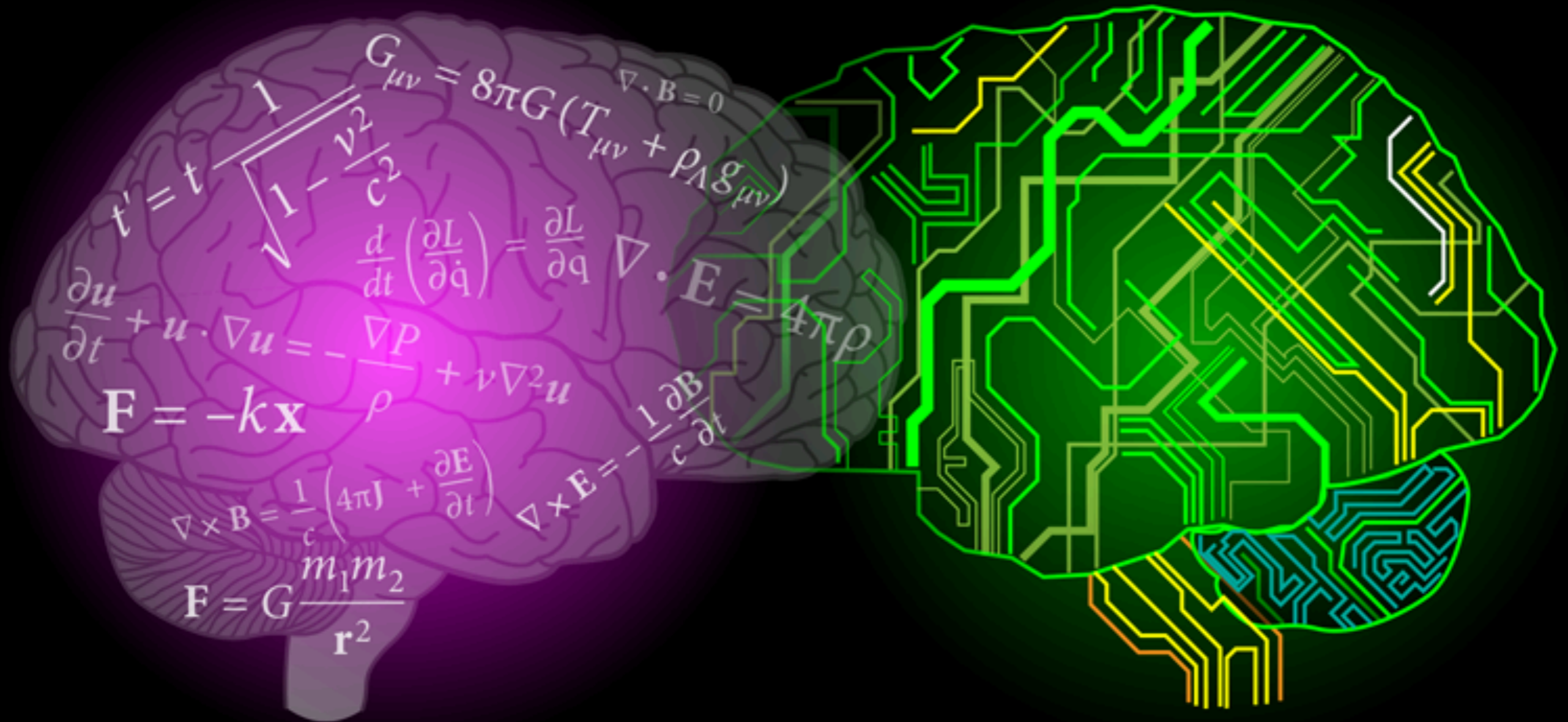
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# Future

**AD in Physics, opportunities and challenges**

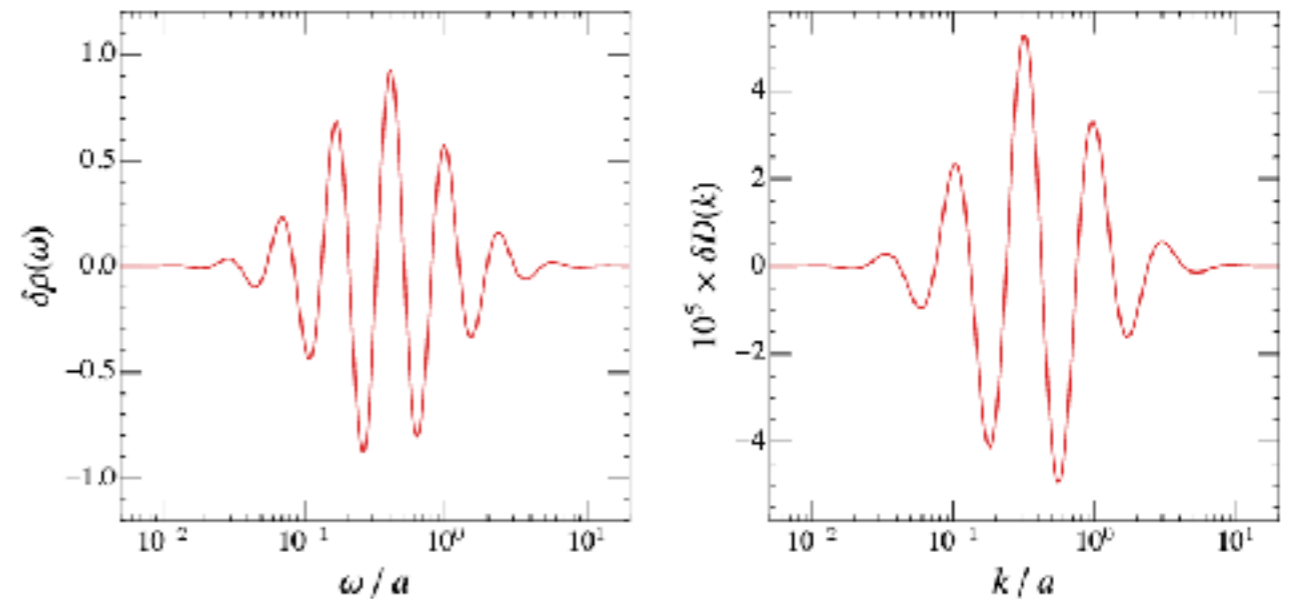
# Backups

- noise cases null-mode

$$\|\rho_1 - \rho_2\|^2 = \sum_{i=\pm} \int_0^{\infty} \left( b_{i,s}^{[\rho_1]} - b_{i,s}^{[\rho_2]} \right)^2 ds,$$

$$\begin{aligned} \|D_1 - D_2\|^2 &= \sum_{i=\pm} \int_0^{\infty} \left( b_{i,s}^{[D_1]} - b_{i,s}^{[D_2]} \right)^2 ds \\ &= \sum_{i=\pm} \int_0^{\infty} \lambda_s^2 \left( b_{i,s}^{[\rho_1]} - b_{i,s}^{[\rho_2]} \right)^2 ds, \end{aligned}$$

- It can be suppressed by regularizations and neural network representations



$f(s)$	$\delta\rho = \int f(s)\psi_{\pm,s}(x)ds$
$(2\pi\sigma^2)^{-\frac{1}{2}} \exp\left[-\frac{(s-s_0)^2}{2\sigma^2}\right]$	$e^{-\frac{\sigma^2 \ln^2(x/a)}{2}} \psi_{\pm,s_0}(x)$
$(2\pi\sigma^2)^{-\frac{1}{2}} \exp\left[-\frac{(s-s_0)^2}{2\sigma^2}\right] \left(\frac{s-s_0}{\sigma}\right)^n$	$e^{-\frac{\sigma^2 \ln^2(x/a)}{2}} \text{H}_n(\sigma \ln(x/a)/\sqrt{2}) \left(\frac{\partial_{x_0}}{\sqrt{2} \ln x}\right)^n \psi_{\pm,s_0}(x)$
$(2\pi\sigma^2)^{-\frac{1}{2}} \exp\left[-\frac{(s-s_0)^2}{2\sigma^2}\right] e^{\frac{\sigma^2 k^2}{2}} \cos[k(s-s_0)]$	$e^{-\frac{\sigma^2 \ln^2(x/a)}{2}} \cosh(\sigma^2 k \ln(x/a)) \psi_{\pm,s_0}(x)$
$(2\pi\sigma^2)^{-\frac{1}{2}} \exp\left[-\frac{(s-s_0)^2}{2\sigma^2}\right] e^{\frac{\sigma^2 k^2}{2}} \sin[k(s-s_0)]$	$\mp e^{-\frac{\sigma^2 \ln^2(x/a)}{2}} \sinh(\sigma^2 k \ln(x/a)) \psi_{\pm,s_0}(x)$

TABLE I: Noise terms with analytical form. Here,  $\text{H}_n$  are the Hermite polynomials.

# Backups

- **Classical MEM**
  - Explicit physical prior
  - Classical optimizers and regularizations
  - Unique solution and uncertainty estimation
- **Supervised Learning**
  - Implicit physical prior (hidden in data)
  - Modern optimizers and regularizations
  - Unique solution? and uncertainty estimation (with Bayesian NN)
- **Our method (NN+AD)**
  - Explicit physical prior (rigorous backward process and physical restrictions)
  - Modern optimizers and regularizations
  - Unique solution and uncertainty estimation (with MEM)