

Cold Quantum Coffee Seminar

# Stabilizing complex Langevin for real-time YM theory

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- 1 Introduction
- 2 Complex Langevin for gauge fields
- 3 Problems of CL for real-time YM and their solution
  - Regularization of the discretized path integral
  - Parametrization dependent CL equation
  - Stabilization of complex Langevin
- 4 Results: Systematic improvement of stability
- 5 Conclusion & Outlook

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- Field theoretic and many-body systems are not solvable analytically
  - ▶ Heavy ion collisions, neutron stars, condensed matter, cold atoms, ...
- Calculations often have to be done numerically or approximations are used (or both)
- Standard numerical integration methods fail for oscillatory integrals
  - ▶ Based on sampling according to some weight function → not applicable for complex weights
  - ▶ Improving accuracy leads to exponentially many samples needed → computationally not feasible
- We miss methods that calculate observables from first principles!

# Schwinger-Keldysh formalism for Yang-Mills theory

## Expectation values in terms of path integrals

$$\langle \mathcal{O}[A] \rangle = \frac{1}{Z} \int \mathcal{D}A_E e^{-S_E[A_E]} \int \mathcal{D}A_+ \mathcal{D}A_- e^{iS[A_+, A_-]} \mathcal{O}(x)$$

- Expectation values of non-local observables in thermal equilibrium

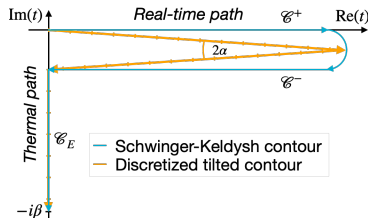
- ▶  $\langle \mathcal{O}_1(t) \mathcal{O}_2(t') \rangle = \text{Tr} [e^{-\beta H} \mathcal{O}_1(t) \mathcal{O}_2(t')]$
- ▶ Only dependent on  $t - t'$  due to time translation invariance
- ▶ Transport coefficients, viscosities, spectral functions, ...

- ▶ Periodic boundary conditions:

$$A_\mu^a(t=0) = A_\mu^a(t=-i\beta)$$

- ▶ Yang-Mills action:

$$S_{\text{YM}} = -\frac{1}{4} \int_{\mathcal{C}} d^4x F_a^{\mu\nu} F_{\mu\nu}^a$$



# Sign problem of real-time YM theory

## Complex weight function leads to the sign problem

- Real-time contour leads to complex weight function

$$\langle \mathcal{O}[A] \rangle = \frac{1}{Z} \int \mathcal{D}A_E e^{-S_E[A_E]} \int \mathcal{D}A_+ \mathcal{D}A_- e^{iS[A_+, A_-]} \mathcal{O}(x)$$

- Direct calculation of oscillatory integrals is not feasible
- Numerical integration methods exponentially costly

## Alternative integration methods needed

- Reweighting, Contour deformation, Analytic continuation, Taylor expansion, Lefschetz thimbles, **Complex Langevin method**, ...

# Reweighting not applicable

- Ideas of reweighting:

- ▶ Split the action in imaginary  $S_R + iS_I = -iS$
- ▶ Reinterpret the observable by multiplying the phase  $\mathcal{O} \rightsquigarrow \mathcal{O}e^{-iS_I}$

$$\begin{aligned}\langle \mathcal{O}_1(t)\mathcal{O}_2(t') \rangle &= \frac{\int \mathcal{D}x e^{-S_R} e^{-iS_I} \mathcal{O}_1(t)\mathcal{O}_2(t)}{\int \mathcal{D}x e^{-S_R} e^{-iS_I}} \\ &= \frac{\int \mathcal{D}x e^{-S_R} e^{-iS_I} \mathcal{O}_1(t)\mathcal{O}_2(t)}{\int \mathcal{D}x e^{-S_R}} \frac{\int \mathcal{D}x e^{-S_R}}{\int \mathcal{D}x e^{-S_R} e^{-iS_I}} \\ &= \frac{\langle \mathcal{O}_1(t)\mathcal{O}_2(t') e^{-iS_I} \rangle_{S_R}}{\langle e^{-iS_I} \rangle_{S_R}}\end{aligned}$$

- Enumerator and denominator can be estimated by MC

- ▶ for the SK integral the average phase vanishes identically, reweighting is not applicable

- Assumption:  $\langle e^{-iS_I} \rangle_{S_R} \neq 0$  (in practice sufficiently large)

- ▶ measure of how “hard” the sign problem is

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# Introduction of the real Langevin method

## Correspondence of Langevin and Fokker-Planck equations

Equivalence by same stationary solution:  $P(\mathbf{x}, \theta \rightarrow \infty) = \exp[-S(\mathbf{x})]$

$$\overbrace{d\mathbf{x} = \mathbf{K}d\theta + d\mathbf{w}}^{SDE} \xLeftrightarrow{\text{It\^o's lemma}} \overbrace{\partial_\theta P(\mathbf{x}, \theta) = \nabla(\nabla - \mathbf{K})P(\mathbf{x}, \theta)}^{PDE} \quad (1)$$

- Langevin time  $\theta$
- Wiener increment/noises term:  $d\mathbf{w}$
- Drift term:  $\mathbf{K} = -\nabla S$
- Averages of some random variable  $X$  depending on  $x$  reduces to sampling from stochastic process

$$\langle X \rangle_P \approx \lim_{\theta_0 \rightarrow \infty} \frac{1}{T} \int_{\theta_0}^{\theta_0+T} d\theta X(\theta)$$

# Introduction of the complex Langevin method

**Idea:** Generalization of correspondence of Langevin and Fokker-Planck equations

Complexification of degrees of freedom:  $\mathcal{M} \ni \mathbf{x} \rightarrow \mathbf{z} = \mathbf{x} + i\mathbf{y} \in \mathcal{M}_c$

$$\left. \begin{aligned} d\mathbf{x} &= \mathbf{K}_x d\theta + d\mathbf{w} \\ d\mathbf{y} &= \mathbf{K}_y d\theta \end{aligned} \right\} \Longleftrightarrow \begin{cases} \partial_\theta P(\mathbf{x}, \mathbf{y}, \theta) = L^T P(\mathbf{x}, \mathbf{y}, \theta) \\ L = \nabla_x (\nabla_x + \mathbf{K}_x) + \nabla_y \mathbf{K}_y \end{cases}$$
$$\stackrel{?}{\Longleftrightarrow} \begin{cases} \partial_\theta \rho(\mathbf{x}, \theta) = L_c^T \rho(\mathbf{x}, \theta) \\ L_c = \nabla_x (\nabla_x + \mathbf{K}) \end{cases}$$

Complex action leads to weight function  $\rho(\mathbf{x}, \theta) \rightarrow \exp[-S(x)]$

- Holomorphic drift term
- Spectrum of  $L_c$  is in the left half plane and 0 is non-degenerate
- Vanishing boundary terms for all (!) moments imply

$$\langle \mathcal{O} \rangle = \int dx dy \mathcal{O}(x + iy) P(x, y, \theta \rightarrow \infty) = \int dx \mathcal{O}(x) \rho(x, \theta \rightarrow \infty)$$

# Complex Langevin method for gauge fields

- CL equation for gauge fields

$$\partial_\theta A_\mu^a(\theta, x) = i \frac{\delta S_{\text{YM}}}{\delta A_\mu^a(t, x)} + \eta_\mu^a(\theta, x)$$

- Complexification of the Lie algebra  $\mathfrak{su}(N_c, \mathbb{C}) \rightarrow \mathfrak{sl}(N_c, \mathbb{C})$
- Gaussian distributed noise term

$$\begin{aligned}\langle \eta_\mu^a(\theta, t, \mathbf{x}) \rangle &= 0, \\ \langle \eta_\mu^a(\theta, t, \mathbf{x}) \eta_\nu^b(\theta', t', \mathbf{x}') \rangle &= 2\delta(\theta - \theta')\delta(t - t')\delta^{(d-1)}(\mathbf{x} - \mathbf{x}')\delta^{ab}\delta_{\mu\nu}\end{aligned}$$

## Goal: Overcoming the sign problem

- CL bypasses the sign problem by sampling at late  $\theta$

$$\langle \mathcal{O}[A] \rangle \approx \lim_{\theta_0 \rightarrow \infty} \frac{1}{T} \int_{\theta_0}^{\theta_0+T} d\theta \mathcal{O}[A(\theta)]$$

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# Three major Problems of CL for real-time YM

- ❶ Discretized path integral along Schwinger-Keldysh contour is non-analytic w.r.t lattice spacing  
→ we tilt the contour to regularize
- ❷ Complex contours give rise to unambiguities in the CL formulation because of the noise correlator (Dirac delta)  
→ we introduce parametrization dependent CL equation
- ❸ CL suffers from instabilities and wrong convergence issues  
→ stabilization techniques needed, we introduce an anisotropic kernel

# Tilted SK contour - Problem 1 ✓

Path integral for Wilson action on a Minkowski time contour has an ill-defined continuum limit!

- Contour deformation resolves non-analyticity

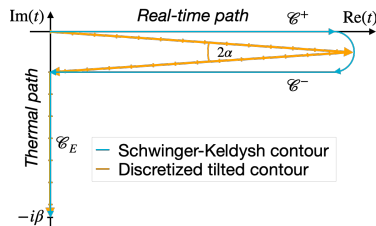
$$\beta_0 \rightarrow e^{+i\alpha} \beta_0, \quad \beta_s \rightarrow e^{-i\alpha} \beta_s$$

- For a SK contour we effectively tilt the real-time paths

$$a_{t,k} \rightarrow e^{-i\alpha} a_{t,k} \quad \text{for } t_k \in \mathcal{C}^+,$$

$$a_{t,k} \rightarrow e^{+i\alpha} a_{t,k} \quad \text{for } t_k \in \mathcal{C}^-$$

- Order of limits is crucial:
  - First  $a_{t,k} \rightarrow 0$  then  $\alpha \rightarrow 0$ .



## Parametrization dependent CL equation

Introduce curve parameter  $\lambda$  for  $t(\lambda)$  leads to

$$\partial_\theta A_\mu^a(\theta, \lambda, \mathbf{x}) = i \left. \frac{\delta S_{\text{YM}}}{\delta A_\mu^a(\lambda, \mathbf{x})} \right|_{A=A(\theta)} + \eta_\mu^a(\theta, \lambda, \mathbf{x}),$$
$$\langle \eta_\mu^a(\theta, \lambda, \mathbf{x}) \eta_\nu^b(\theta', \lambda', \mathbf{x}') \rangle = 2\delta_{\mu\nu} \delta^{ab} \delta(\theta - \theta') \delta(\lambda - \lambda') \delta^{(3)}(\mathbf{x} - \mathbf{x}')$$

- Complex time contours leads to ambiguous noise correlator expression ( $\delta$ -distribution for complex arguments)
  - ▶ Ambiguities are resolved by a parametrization dependent CL formulation

$$t : [a, b] \mapsto \mathbb{C}, \quad t(a) = 0, \quad t(b) = -i\beta$$

- ▶ Noise correlator in terms of  $\lambda$

$$\delta(t(\lambda) - t(\lambda')) \rightsquigarrow \delta(\lambda - \lambda')$$

- Solution is however independent of the chosen parametrization
- Limiting cases (Minkowski and Euclidean contour) are consistent with new formulation

# Some lattice QCD...

- Link variables and plaquette variables

$$U_{x,\mu} \simeq \exp \left[ i g a_\mu A_\mu \left( x + \hat{\mu}/2 \right) \right] \in \text{SU}(N_c) \rightsquigarrow \text{SL}(N_c, \mathbb{C}),$$
$$U_{x,\mu\nu} = U_{x,\mu} U_{x+\hat{\mu},\nu} U_{x+\hat{\nu},\mu}^{-1} U_{x,\nu}^{-1}$$

- Wilson plaquette action

$$S_W[U] = \frac{1}{2N_c} \sum_{k,\mathbf{x},\mu \neq \nu} \beta_{\mu\nu} \text{Tr} [U_{x,\mu\nu} - 1],$$

- Coupling constants

$$\beta_{0i} = -\frac{2N_c}{g^2} \frac{a_s}{a_{t,k}}, \quad \beta_{ij} = +\frac{2N_c}{g^2} \frac{\bar{a}_{t,k}}{a_s}$$

- Time reversibility is retained by averaged spacing (turning points of the SK contour!)

$$\bar{a}_{t,k} = (a_{t,k} + a_{t,k+1})/2$$



## CL update step for link variables on a SK-contour

- Discretization of contour parameter
- Additional lattice spacing factors compared to common CL-step [1]

$$U_{x,t}(\theta + \epsilon) = \exp \left( it^a \left[ i\epsilon \frac{\mathbf{a}_{\lambda,k}}{\mathbf{a}_s} \frac{\delta S_W}{\delta \tilde{A}_{x,t}^a} \Big|_{\theta} + \sqrt{\epsilon} \sqrt{\frac{\mathbf{a}_{\lambda,k}}{\mathbf{a}_s}} \eta_{x,\lambda}^a(\theta) \right] \right) U_{x,t}(\theta)$$

$$U_{x,i}(\theta + \epsilon) = \exp \left( it^a \left[ i\epsilon \frac{\mathbf{a}_s}{\bar{\mathbf{a}}_{\lambda,k}} \frac{\delta S_W}{\delta \tilde{A}_{x,i}^a} \Big|_{\theta} + \sqrt{\epsilon} \sqrt{\frac{\mathbf{a}_s}{\bar{\mathbf{a}}_{\lambda,k}}} \eta_{x,i}^a(\theta) \right] \right) U_{x,i}(\theta)$$

- Langevin time step  $\epsilon \rightarrow 0$
- Noise  $\eta_{x,i}^a$  is approximated by a Gaussian distribution
- $\sqrt{\frac{a_s}{\bar{a}_{\lambda,k}}}$  leads to issues in the  $N_t \rightarrow \infty$  limit

## CL suffers from instabilities

- Runaway instabilities  
→ numerical blow-up due to excursions into the non-compact manifold
- Wrong-convergence issues  
→ distorted expectation values due to violation of the criterion of correctness

**Bad:** We are facing both types of instabilities for YM on a SK contour

***Even worse:*** Severity of the instabilities drastically increases with shrinking tilt-angles → limit to SK contour difficult

# Existing stabilization techniques

- **Gauge cooling [2]:** Exploit gauge freedom to minimize non-unitarity measured by a functional  $F[U]$

$$U_{x,\mu} \mapsto U_{x,\mu}^V = V_x U_{x,\mu} V_{x+\mu}^{-1}, \quad F[U] \geq F[U^V]$$

- **Adaptive stepsize [3]:** Regulate large drift terms which lead to instabilities

$$\epsilon \mapsto \tilde{\epsilon} = \epsilon \min \left( 1, \frac{B}{\max_{x,\mu,a} |K_{x,\mu}^a|} \right)$$

- **Dynamical stabiliziation [4]:** Penalize drift terms depending on the local non-unitary of the configuration

$$K_{x,\mu}^a \mapsto \tilde{K}_{x,\mu}^a = K_{x,\mu}^a + i\alpha_{\text{DS}} M_x^a,$$
$$M_x^a = b_x^a \left( \sum_c b_x^c b_x^c \right), \quad b_x^a = \sum_{\mu} \text{Tr}[t^a U_{x,\mu} U_{x,\mu}^\dagger]$$

## Field-independent kernel freedom

- *Kerneled Langevin equation* yields same limiting density function

$$\partial_{\theta} A_{\mu}^a(\theta, x) = i \int dx' \Gamma_{\mu\nu}^{ab}(x, x') \frac{\delta S}{\delta A_{\nu}^b(x')} + \int dx' \tilde{\Gamma}_{\mu\nu}^{ab}(x, x') \eta_{\nu}^b(\theta, x')$$

- $\Gamma_{\mu\nu}^{ab}(x, x')$  is required to be factorizable

$$\Gamma_{\mu\nu}^{ab}(x, x') = \int dx'' \tilde{\Gamma}_{\mu\sigma}^{ac}(x, x'') \tilde{\Gamma}_{\nu\sigma}^{bc}(x', x'')$$

- Kerneled Langevins equations correspond to the same Fokker-Planck equations (equivalence classes)
- *In practice:* Kernels may aggravate or mitigate instabilities

## Kerneled CL update step

- Rescaling of Langevin time for temporal and spatial d.o.f.

$$U_{x,t}(\theta + \epsilon) = \exp \left( it^a \left[ i\epsilon \left( \frac{a_{\lambda,k}}{a_s} \right)^2 \frac{\delta S_W}{\delta \tilde{A}_{x,t}^a} \Big|_{\theta} + \sqrt{\epsilon} \frac{a_{\lambda,k}}{a_s} \eta_{x,\lambda}^a(\theta) \right] \right) U_{x,t}(\theta)$$

$$U_{x,i}(\theta + \epsilon) = \exp \left( it^a \left[ i\epsilon \frac{\delta S_W}{\delta \tilde{A}_{x,i}^a} \Big|_{\theta} + \sqrt{\epsilon} \eta_{x,i}^a(\theta) \right] \right) U_{x,i}(\theta)$$

## Empirical motivation for chosen kernel:

- Noise of spatial update blows up for  $a_{\lambda,k} \rightarrow 0$   $\rightsquigarrow \theta \mapsto \frac{\bar{a}_{\lambda,k}}{a_s} \theta$
- Slow down dynamics of temporal plaquettes  $\rightsquigarrow \theta \mapsto \frac{a_{\lambda,k}}{a_s} \theta$

# Comparison

## Commonly used CL update step [1]

$$U_{x,\mu}(\theta + \epsilon) = \exp \left( it^a \left[ i\epsilon \frac{\delta S_W}{\delta A_{x,\mu}^a} \Big|_{\theta} + \sqrt{\epsilon} \eta_{x,\mu}^a(\theta) \right] \right) U_{x,\mu}(\theta)$$

## New kerneled CL update step

$$U_{x,t}(\theta + \epsilon) = \exp \left( it^a \left[ i\epsilon \left( \frac{a_{\lambda,k}}{a_s} \right)^2 \frac{\delta S_W}{\delta \tilde{A}_{x,t}^a} \Big|_{\theta} + \sqrt{\epsilon} \frac{a_{\lambda,k}}{a_s} \eta_{x,\lambda}^a(\theta) \right] \right) U_{x,t}(\theta)$$

$$U_{x,i}(\theta + \epsilon) = \exp \left( it^a \left[ i\epsilon \frac{\delta S_W}{\delta \tilde{A}_{x,i}^a} \Big|_{\theta} + \sqrt{\epsilon} \eta_{x,i}^a(\theta) \right] \right) U_{x,i}(\theta)$$

**We see great interconnection of the three proposed solutions:**

- Path integral regularization is done by contour deformation (tilting)
- Tilted contours (non-real, non-imaginary) can be dealt with by parameterized CL formulation
- Calculation of physical observables requires a double-extrapolation

$\Rightarrow$  first  $a_t \rightarrow 0$ , second  $\alpha \rightarrow 0$

- Kernel systematically improves stability for smaller  $a_t$

**Instabilities get worse for  $\alpha \rightarrow 0$  and are counteracted by our kernel for  $a_t \rightarrow 0$ !**

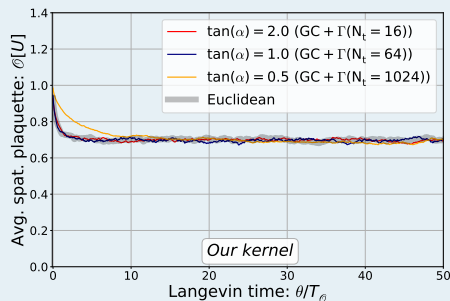
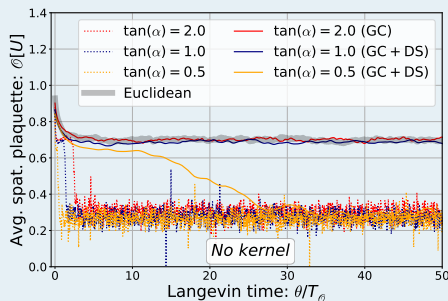
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- We simulate  $SU(2)$  gauge theory on a  $N_t \times 4^3$  lattice
- Kernel is controlled by number of temporal lattice points  $N_t$
- Inverse temperature  $\beta = 4.0$ , coupling constant  $g = 1$ 
  - ▶ We are in the deconfined phase ( $\langle |P| \rangle \neq 0$ ).
- Simulations are initialized with identity matrices
- Same seed for random number generator for noise
- Langevin time is rescaled by the autocorrelation time

# Correct expectation values of one-point functions

## Trace of average spatial plaquette



- Avg. spatial plaquette (considered in earlier studies [1]):

$$\mathcal{O}[U] = \frac{1}{N_t N_s^3} \sum_x \frac{1}{3} \sum_{i < j} \frac{1}{N_c} \text{ReTr } U_{x,ij}$$

- Existing methods not enough for stabilizing simulations
- **Kernels successfully stabilizes even small tilt angles**

# Expectation values from CL

**Results for average spatial plaquette  $\mathcal{O}$  via CL:**

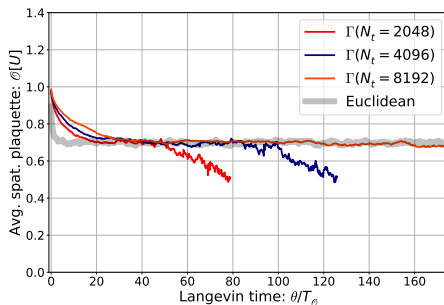
$\tan(\alpha)$	Stabilization techniques	$N_t$	$\langle \mathcal{O} \rangle$
(Euclidean)	None	16	0.6992(3)
2.0	AS, GC	16	0.6981(2)
1.0	AS, GC, DS	16	0.6858(1)
0.5	AS, GC, DS	16	0.2801(3)
2.0	AS, GC, $\Gamma$	16	0.6987(3)
1.0	AS, GC, $\Gamma$	64	0.6977(5)
0.5	AS, GC, $\Gamma$	1024	0.6973(8)
0.4	AS, GC, $\Gamma$	8192	0.6968(6)

# Systematic improvement of CL instabilities

## Anisotropic kernel systematically stabilizes CL

- Our kernel allows simulations even for  $\max \text{Re}(t) > \beta$
- Stability is systematically improved for partial continuum limit  
 $\Rightarrow$  **Calculation of real-time observables might be feasible!**

- Stability region grows faster than auto-correlation time w.r.t.  $N_t$
- Computational cost grows linearly with  $N_t$



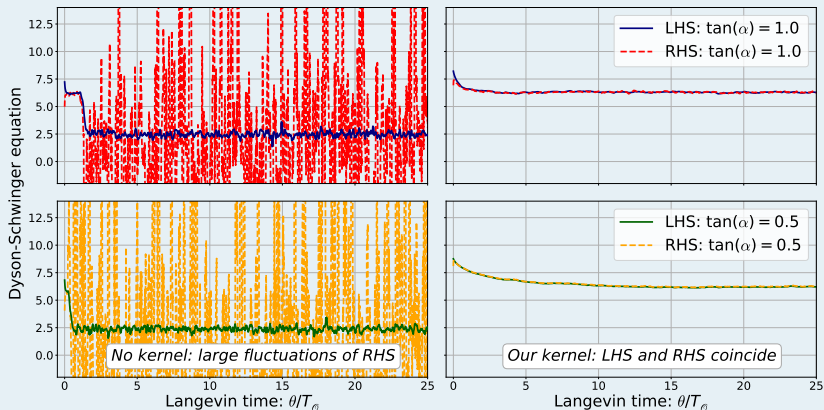
*Tilt angle:  $\tan(\alpha) = 0.4$*

# Dyson-Schwinger equations

## DSE for spatial plaquettes

- Self-consistency check of link configuration

$$\frac{2(N_c^2 - 1)}{N_c} \langle \text{ReTr}(U_{x,ij}) \rangle = \frac{i}{2N_c} \sum_{|\rho| \neq i} \beta_{i\rho} \langle \text{ReTr} [(U_{x,i\rho} - U_{x,i\rho}^{-1}) U_{x,ij}] \rangle$$

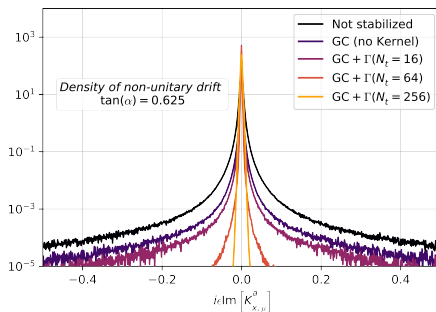


# Localized histogram of the drift terms

## Anisotropic kernel and the criterion of correctness

- We implicitly assume that  $K_y PO$  decay sufficiently fast
- Localised histograms of the  $K_y$  should lead to vanishing boundary terms

- Gauge cooling helps, but skirts are still present
- No skirts of histograms using our kernel with sufficiently large  $N_t$



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## Conclusion





- Stabilization techniques extend the applicability of CL
- We found an approach to systematically improve stability
- Anisotropic kernel enables simulations of  $\max \text{Re}(t) > \beta$ 
  - $\leadsto$  Extrapolation to Schwinger-Keldysh contour might be possible
- What I have shown you
  - ▶ Average spatial plaquette
  - ▶ Dyson-Schwinger equations
  - ▶ Histograms of the drift term
- What I have *not* shown you
  - ▶ Larger Wilson loops ( $W_{n \times n}$ )
  - ▶ Polyakov loop
  - ▶ Unitarity norm
  - ▶ Euclidean correlators



# Teaser of our most recent results

## Outlook

- Checks of mathematical features of correlation function
  - ▶ Independence  $\frac{t+t'}{2}$
  - ▶ Relations of Wightman functions and Propagators
  - ▶ Fluctuation-dissipation relation
- Calculation of physical lattice spacing (ongoing)
  - ▶ Renormalization needed for physical observables
- Bulk and shear spectral function (ongoing)
  - ▶ We carry out the double extrapolation
  - ▶ We are able to simulate real-time extents of  $t_{\max} = 4\beta$
- Far-future prospect: Non-thermal quantum systems

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