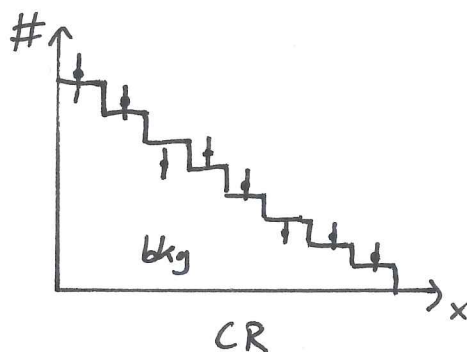
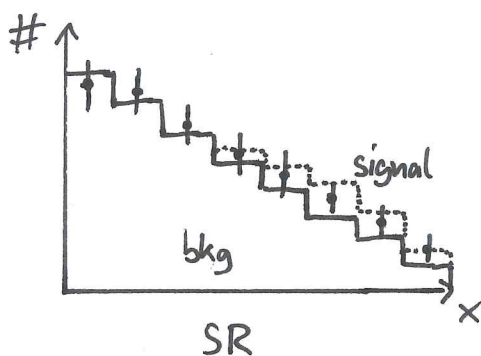


Statistical Methods & Confidence Intervals

Goal of these lectures:

- derive confidence interval for signal strength μ in this example:



- two regions (SR, CR) each with observed # events n_i and expected # events v_i (from MC) per bin

Lecture 1

Probability:

- defined by Kolmogorov axioms:

1) $P(A) \geq 0$ for any event A

2) $P(\Omega) = 1$ Ω : samplespace (all possible outcomes)

3) $A \cap B = \emptyset \Rightarrow P(A \cup B) = P(A) + P(B)$

- different interpretations of such a probability:

Frequentist (aka. Classical)	Bayesian
A : result of repeatable experiment	A : hypothesis
$P(A) = \lim_{n \rightarrow \infty} \frac{\#A}{n}$	$P(A)$ = degree of belief that A is true
caveats: <ul style="list-style-type: none"> • $n \rightarrow \infty$ impossible • non-repeatable experiments? • $P(A)$ not intrinsic to A but property of ensemble 	<ul style="list-style-type: none"> • highly subjective • how to quantify?

"Bayesians address the questions everyone is interested in by using assumptions that no one believes. Frequentists use impeccable logic to deal with an issue that is of no interest to anyone."

Bayes theorem:

- follows from definition of conditional probability

$$P(A|B) \cdot P(B) \equiv P(A \cap B) \equiv P(B|A) \cdot P(A)$$

$$\Rightarrow P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$

- for our example:

$A \rightarrow$ hypothesis H (with parameter μ)

$B \rightarrow$ observation x

$P \rightarrow$ probability density p (μ continuous)

$$P(H|x) = \frac{\overbrace{p(x|H)}^{\text{likelihood}} \cdot \overbrace{p(H)}^{\text{prior}}}{\int p(x|H) \cdot p(H) dH} \quad \} \text{ normalization}$$

posterior

Bayesian: $\cdot p(H|x) dH$ is the probability that H is true

Frequentist: $\cdot H$ is either true or not, no probability assigned

$\cdot p(H|x) dH$ is the ratio that H is true in infinite repetitions

Likelihood:

- $\mathcal{L}(H|x) \equiv p(x|H)$ (sometimes also written $\mathcal{L}(H)$ or $\mathcal{L}(x|H)$)

where p : fct. of observation x for fixed H

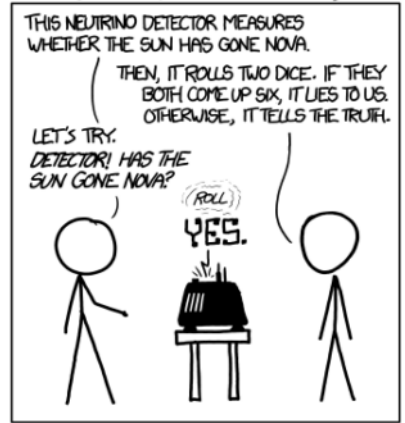
$$\int p(x|H) dx = 1$$

\mathcal{L} : fct. of H for fixed observation x

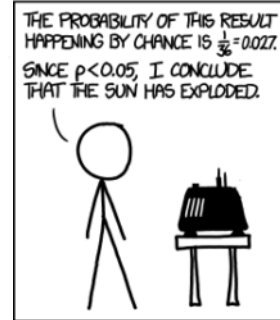
$$\int \mathcal{L}(H|x) dH \neq 1$$

- exact shape will depend on specific problem, but typically written as joint PDF of several standard PDF's

DID THE SUN JUST EXPLODE?
(IT'S NIGHT, SO WE'RE NOT SURE.)



FREQUENTIST STATISTICIAN:



BAYESIAN STATISTICIAN:



	PDF	$(\int x p(x) dx)$ EV	$(\int (x-\mu)^2 p(x) dx)$ variance
Gauss	$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp[-\frac{(x-\mu)^2}{2\sigma^2}]$	μ	σ^2
multivariate Gauss	$p(\vec{x}) \propto \exp[-\frac{1}{2}(\vec{x}-\vec{\mu})^T V^{-1}(\vec{x}-\vec{\mu})]$	$\vec{\mu}$	V
Poisson	$p(k) = \frac{\mu^k}{k!} e^{-\mu}$	μ	μ
Binomial	$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$	np	$np(1-p)$
Uniform	$p(x) = \begin{cases} \frac{1}{b-a} & , a \leq x \leq b \\ 0 & , \text{else} \end{cases}$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
Exponential	$p(x) = \begin{cases} \frac{1}{\tau} \exp(-x/\tau) & , x \geq 0 \\ 0 & , \text{else} \end{cases}$	τ	τ^2
Cauchy / Breit-Wigner	$p(x) \propto \frac{\Gamma}{(x-\mu)^2 + (\Gamma/2)^2}$	undef	undef

- non-converging integrals $\int x p(x) dx$ and $\int x^2 p(x) dx$
- can be approximated Gaussian close to peak if $\Gamma \ll \mu$

for our example:

- individual bins are independent counting experiments \Rightarrow joint PDF factorizes:

$$p(\vec{n} | \vec{v}) = \prod_i p(n_i | v_i)$$

- What about systematics?

\rightarrow parametrize them via nuisance parameters θ

$$\vec{v} = \vec{v}(\mu, \vec{\theta})$$

$$\mathcal{L}_{SR} = \mathcal{L}_{SR}(\mu, \vec{\theta} | \vec{n}) = \prod_{i \in SR} p(n_i | v_i(\mu, \vec{\theta})) \underbrace{\prod_{j \in syst} q_j(\theta_j | \tilde{\theta}_j)}_{\text{prior of systematic}}$$

$\tilde{\theta}_j$ nominal value

$$\mathcal{L}_{CR} = \text{---}$$

$$\mathcal{L}_{tot}(\mu, \vec{\theta} | \vec{n}) = \prod_{i \in SR, CR} p(n_i | v_i(\mu, \vec{\theta})) \prod_{j \in syst} q_j(\theta_j | \tilde{\theta}_j)$$

\rightarrow this is identical to constructing the posterior $p(\mu, \vec{\theta} | \vec{n})$ via Bayes theorem with flat prior for μ (neglecting the normalization)

\rightarrow we can combine different measurements by multiplying their likelihoods (careful not to count syst. priors twice!)

• What is $p(n_i | \nu_i)$?

- typically each bin is counting exp. \rightarrow Poissonian
- if any post-processing applied to observed spectrum (e.g. unfolding), p in general no longer Poissonian
 - \rightarrow can often be approximated Gaussian in this case
 - \rightarrow if bin-to-bin correlations introduced, use multivariate Gaussian or diagonalize
 - \rightarrow can also use histogrammed PDF obtained via bootstrapping

• What is $q_j(\theta_j | \tilde{\theta}_j)$?

\rightarrow depends on systematic!

- detector syst. • typically considered Gaussian
 - typically parametrized s.t. $\tilde{\theta} = 0$ and variance = 1
 - $\Rightarrow \nu_i(\tilde{\theta}) = \nu_i(\tilde{\theta}) + \sum_j \theta_j \cdot \underbrace{S_j(\nu_i)}_{\text{impact of } \theta_j \text{ on } \nu_i}$
estimated by varying it $\pm 1\sigma$

e.g. $q_{\theta \in s} = \mathcal{N}(0, 1)$

• $q_{\text{renorm}} = \begin{cases} 1/2 & -1 \leq \theta \leq 1 \\ 0 & \text{else} \end{cases}$

• $q_{\text{scalefac}} \propto 1$

• $q_{\text{MCstat}, i} = \mathcal{N}(0, 1)$

• $q_{\text{BR}(H \rightarrow b\bar{b})} = \mathcal{N}(0.58, 0.02)$

\vdots