

Precision Forward and Inverse Simulations for the LHC

Tilman Plehn

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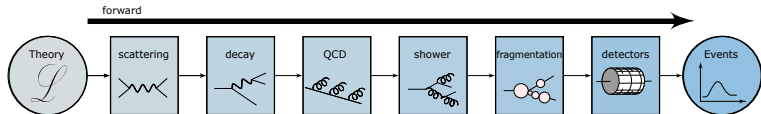
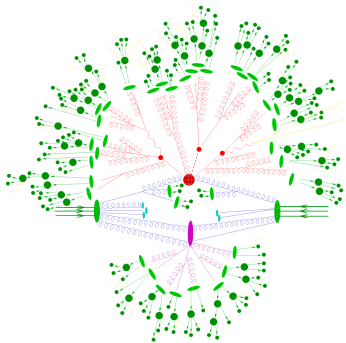
Bern, March 2022



First-principle simulations

Simulation-based inference [likelihood-free inference]

- understand events completely
 - Lagrangian to start
 - perturbative QFT
 - event generation [Sherpa, Madgraph, Pythia, Powheg]
 - detector simulation
- LHC events in virtual worlds



First-principle simulations

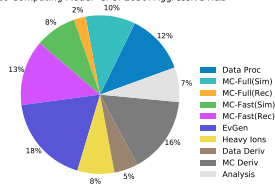
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Forward LHC simulations

- HL-LHC: preparing for 25-fold data set
 - simulated events \sim expected events
 - 1%-2% statistical uncertainty [NNLO/N³LO]
 - low-rate high-multiplicity processes
 - time-dependent signal hypotheses
- Event generation limiting factor

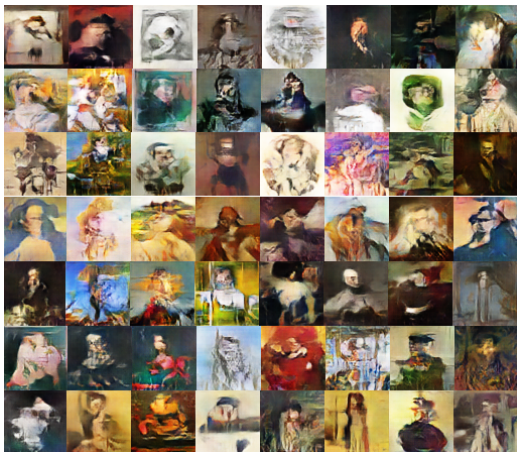
ATLAS Preliminary
2020 Computing Model -CPU: 2030: Aggressive R&D



Generative networks

GANgogh [Bonafilia, Jones, Danyluk (2017)]

- neural network — learned function by minimizing loss
 - regression $x \rightarrow f(x)$
 - classification $x \rightarrow p(x) \in [0, 1]$
 - generation $x \rightarrow p_X(x)$ sampled $x \sim \mathcal{N}$
- networks to create **new pieces of art**
- train on 80,000 pictures
- generate portraits



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- trained on 15,000 portraits
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LHC examples

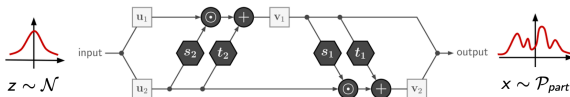
- **jets** [Nachman (2017), Carrazza-Dreyer (2019)...]
- **events** [Butter (2019), Review (2020)...]
- **detector** [Nachman (2017), Erdmann (2018), Kasieczka (2020), Krause-Shih (2021)...]
- **unfolding** [Omnifold, cGAN, cINN (2020)...]
- **inference** [QCD splittings (2020)...]
- **compression** [Rabemananjara (2021), ephemeral (2022)...]



Uncertain normalizing flows

Normalizing flows — INN [Ardizzone, Köthe]

- Gaussian latent space
 - bijective mapping
 - known Jacobian
 - log-likelihood loss
- Better than VAEs and GANs



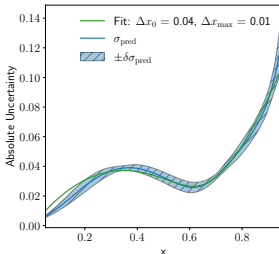
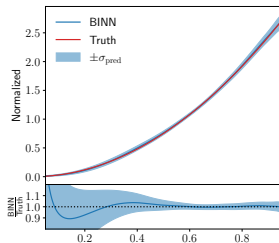
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Bayesian INNs [Bellagente, Haußmann, Luchmann, TP]

- network weight distributions [Gal (2016)]
 - sample for output [efficient ensembling]
 - working for regression, classification
 - events with error bars [density & uncertainty maps]
 - 2D: wedge ramp, kicker ramp,...
- INNs just fits



Precision generator

ML-event generators [Butter, Plehn..., CaloFlow: Krause & Shih]

- useful ML-playground
- training from event samples
no momentum conservation
no detector effects [sharper structures]

1- top-quark pairs $t\bar{t} \rightarrow 6$ jets [resonance peaks]

2- $Z_{\mu\mu} + \{1, 2, 3\}$ jets [Z-peak, variable jet number, jet-jet topology]



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INN-generator [Butter, Heimele, Hummerich, Krebs, TP, Rousselot, Vent]

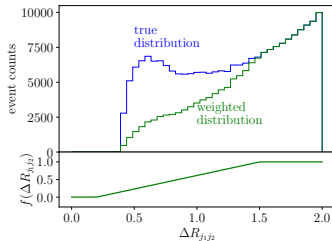
- challenging ΔR_{jj} features
- opposite of importance sampling

$$w^{(1\text{-jet})} = 1$$

$$w^{(2\text{-jet})} = f(\Delta R_{j_1, j_2})$$

$$w^{(3\text{-jet})} = f(\Delta R_{j_1, j_2})f(\Delta R_{j_2, j_3})f(\Delta R_{j_1, j_3})$$

$$f(\Delta R) = \frac{\Delta R - R_-}{R_+ - R_-} \quad (\Delta R \in [R_-, R_+])$$



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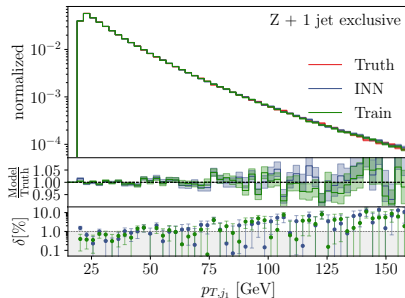
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→ Per-cent precision in reach



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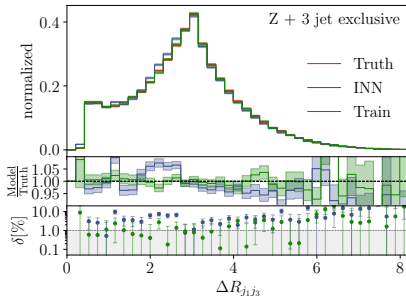
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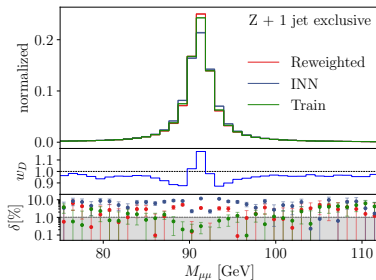
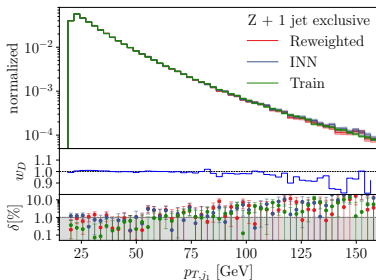
→ Per-cent precision in reach



Controlled precision generator

Discriminator: training vs generated

- input $\{p_T, \eta, \phi, M, M_{\mu\mu}, \Delta R\}$
 - output $D = 0(\text{generator}), 1(\text{truth})$
 - decent generator training $D \approx 0.5$
 - additional event weight $w_D = D/(1 - D) \rightarrow 1$
- Dual use — control & reweight



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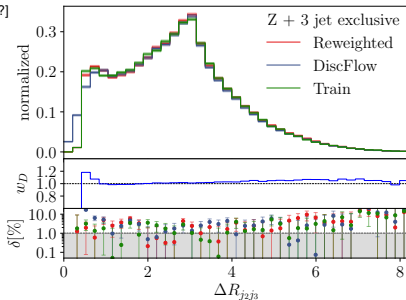
Joint DiscFlow training [GAN inspiration]

- adversarial loss unstable [Nash equilibrium??]
- coupling through weights

$$L_{\text{DiscFlow}} = - \sum_{i=1}^B w_D(x_i)^\alpha \log \frac{P(x_i)}{P_{\text{ref}}(x_i)}$$

$$\approx - \int dx \frac{P_{\text{ref}}^{\alpha+1}(x)}{P^\alpha(x)} \log \frac{P(x)}{P_{\text{ref}}(x)}$$

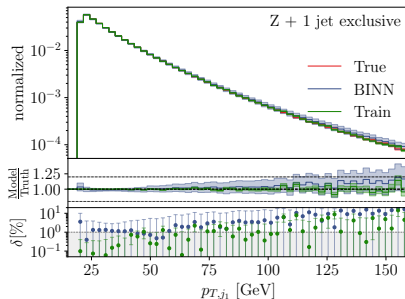
→ Per-cent precision



Uncertain precision generator

BINN generator

- Bayesian precision generator
 - uncertainty over phase space
 - low statistics challenging
- Training-related error bars



Uncertain precision generator

BINN generator

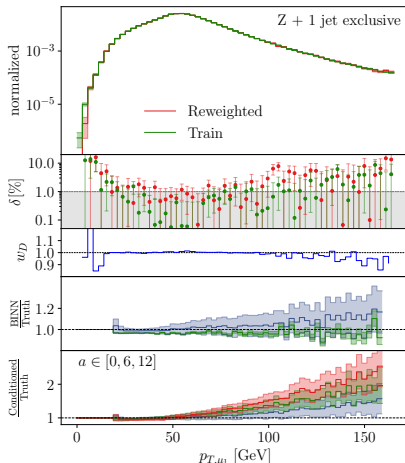
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 - low statistics challenging
- Training-related error bars

Theory uncertainties

- systematics from data augmentation
- adjust data in tails [$a = 0 \dots 30$]

$$w = 1 + a \left(\frac{p_{T,j_1} - 15 \text{ GeV}}{100 \text{ GeV}} \right)^2$$

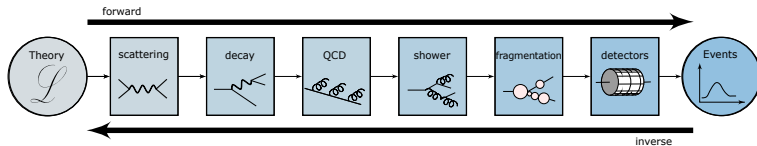
- train conditionally on smeared a
 - error bar from sampling a
- INN for LHC standards



Inverse simulation

Invertible ML-simulation [see also Ben Nachman's seminar]

- detector unfolding known problem
 - QCD parton from jet algorithm standard
 - jet radiation combinatorics challenge
 - decays established by top groups
 - matrix element method the dream
- multi-dimensional, unbinned, statistical?



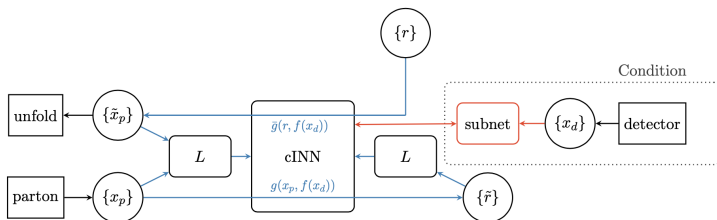
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Conditional INN [Bellagente, Butter, Kasieczka, TP, Rousselot, Winterhalder, Ardizzone, Köthe]

- partonic events from $\{r\}$, given detector event



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Conditional INN [Bellagente, Butter, Kasieczka, TP, Rousselot, Winterhalder, Ardizzone, Köthe]

- partonic events from $\{r\}$, given detector event
- maximum likelihood loss

$$\begin{aligned} L &= - \langle \log p(\theta | x_p, x_d) \rangle_{x_p, x_d} \\ &= - \left\langle \log p(g(x_p, x_d)) + \log \left| \frac{\partial g(x_p, x_d)}{\partial x_p} \right| \right\rangle_{x_p, x_d} - \log p(\theta) + \text{const.} \end{aligned}$$

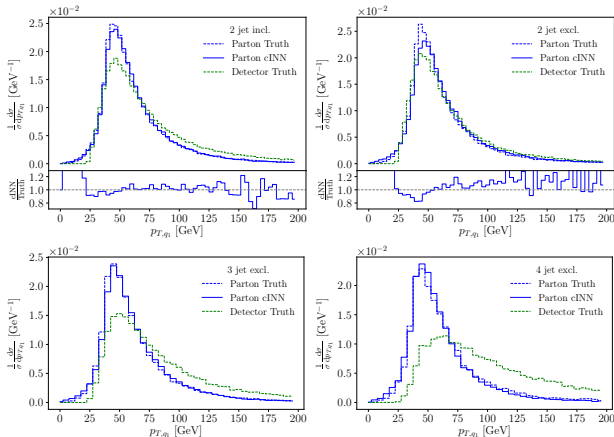
→ Stable and statistically calibrated



Inverting to hard process

Undo QCD jet radiation

- nasty jet combinatorics, little information
- detector level: $pp \rightarrow ZW + \text{jets}$ [variable number of objects]
- hard process given, ME vs PS jets from network



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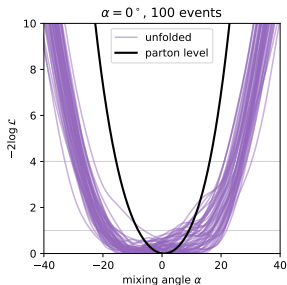
Matrix element method [Butter, Heimgel, Martini, Peitzsch, TP (soon)]

- parameter likelihood from parton-level events

$$\mathcal{L}(\theta) = \prod_{i=1}^N p(\vec{x}^{(i)} | \theta) = \prod_{i=1}^N \frac{1}{\sigma_{\text{fid}}(\theta)} \int d^m z \frac{d^m \sigma(\theta)}{dz_1 \dots dz_m} T(\vec{x}^{(i)}, \vec{z})$$

$$T(\vec{x}, \vec{z}) = p_{\text{INN}}(\vec{z} | \vec{x}) \epsilon(\vec{x}) \quad \Rightarrow \quad \mathcal{L}(\theta) = \prod_{i=1}^N \frac{\epsilon(\vec{x}^{(i)})}{\sigma_{\text{fid}}(\theta)} \int d^m z \frac{d^m \sigma(\theta)}{dz_1 \dots dz_m} p_{\text{INN}}(\vec{z} | \vec{x}^{(i)})$$

$$= \prod_{i=1}^N \frac{\epsilon(\vec{x}^{(i)})}{\sigma_{\text{fid}}(\theta)} \left\langle \frac{d^m \sigma(\theta)}{dz_1 \dots dz_m} \right\rangle_{\vec{z} \sim p_{\text{INN}}}$$



Inverting to QCD

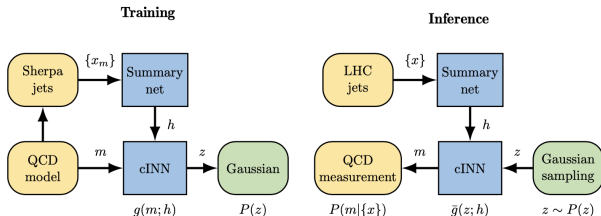
cINN for inference [Bieringer, Butter, Heimes, Höche, Köthe, TP, Radev]

- condition jets with QCD parameters
- train model parameters \rightarrow Gaussian latent space
- test Gaussian sampling \rightarrow parameter measurement
- beyond C_A vs C_F [Kluth et al]

$$P_{qq} = C_F \left[D_{qq} \frac{2z(1-y)}{1-z(1-y)} + F_{qq}(1-z) + C_{qq}yz(1-z) \right]$$

$$P_{gg} = 2C_A \left[D_{gg} \left(\frac{z(1-y)}{1-z(1-y)} + \frac{(1-z)(1-y)}{1-(1-z)(1-y)} \right) + F_{gg}z(1-z) + C_{gg}yz(1-z) \right]$$

$$P_{qg} = T_R \left[F_{qg} (z^2 + (1-z)^2) + C_{qg}yz(1-z) \right]$$



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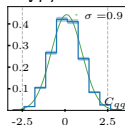
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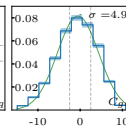
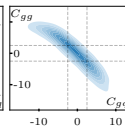
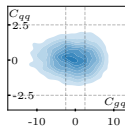
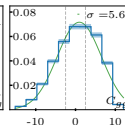
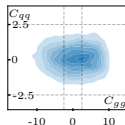
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$$P_{qg} = T_R \left[F_{qq} (z^2 + (1-z)^2) + C_{qg}yz(1-z) \right]$$

- idealized shower [Sherpa]
- More ML-opportunities...



— Posterior
— Gaussian fit
- - Absolute error of 2.5



ML for LHC Theory

ML-applications in LHC analysis and theory

- just another numerical tool for a numerical field
 - driven by money from data science, medical research
 - goals are...
 - ...improve established tasks
 - ...develop new tools for established tasks
 - ...transform through new ideas
 - particle physics as exciting as our ideas
- Opportunity to make a difference!

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Machine Learning and LHC Event Generation

Anja Butter^{1,2}, Tilman Plehn¹, Steffen Schumann³ (Editors),
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Abstract

First-principle simulations are at the heart of the high-energy physics research program. They link the vast data output of multi-purpose detectors with fundamental theory predictions and interpretation. This review illustrates a wide range of applications of modern machine learning to event generation and simulation-based inference, including conceptual developments driven by the specific requirements of particle physics. New ideas and tools developed at the interface of particle physics and machine learning will improve the speed and precision of forward simulations, handle the complexity of collision data, and enhance inference as an inverse simulation problem.

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